

EFFECT HANDLERS & MATHEMATICALLY INSPIRED LANGUAGE CONSTRUCTS

Matija Pretnar



FMF

UNIVERSITY OF LJUBLJANA
Faculty of Mathematics and Physics

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HANDLERS

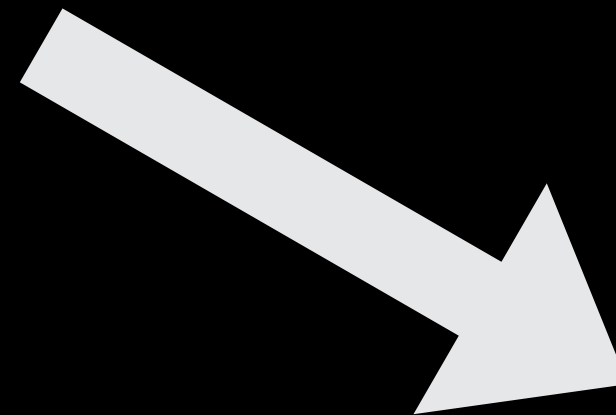
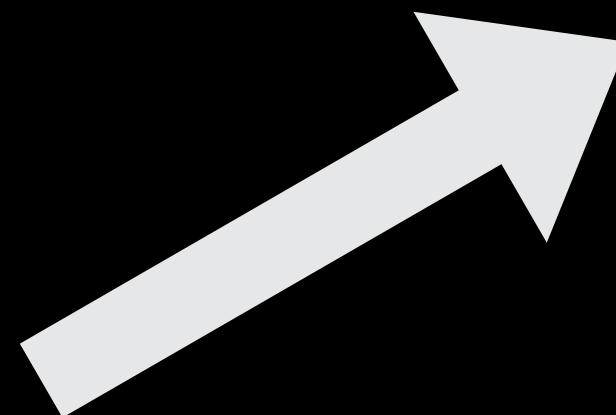
HANDLERS



HANDLERS

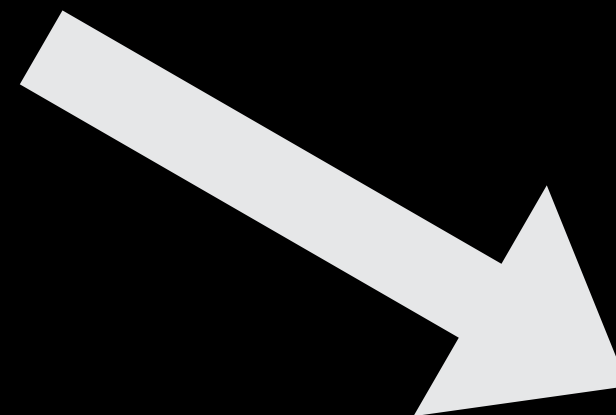
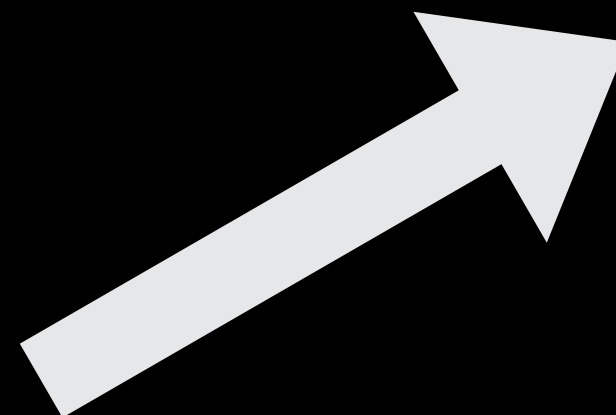


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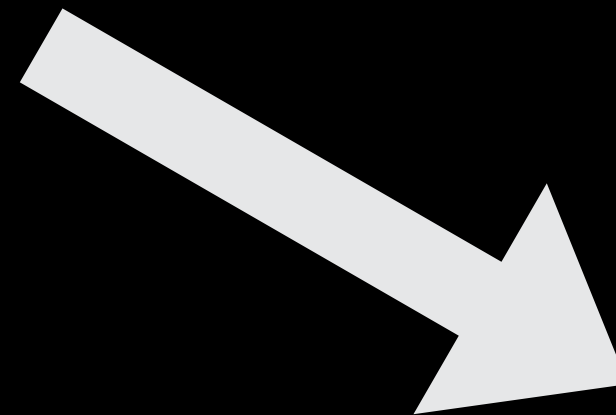
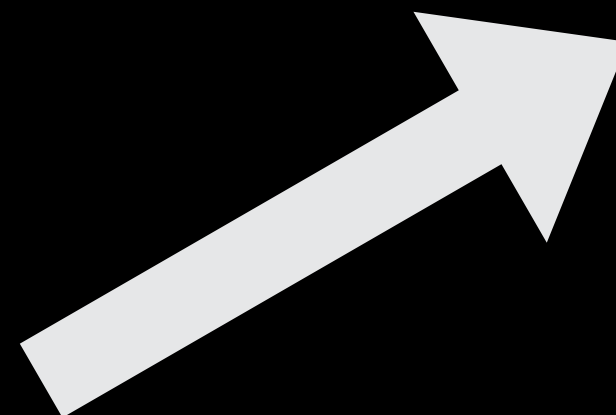


HANDLERS





HANDLERS



Moggi recognised **monads** in the **semantics** of effectful computations

Computational lambda-calculus and monads

Eugenio Moggi*
Lab. for Found. of Comp. Sci.
University of Edinburgh
EH9 3JZ Edinburgh, UK
On leave from Univ. di Pisa

Abstract

The λ -calculus is considered an useful mathematical tool in the study of programming languages. However, if one uses $\beta\eta$ -conversion to prove equivalence of programs, then a gross simplification¹ is introduced. We give a calculus based on a categorical semantics for *computations*, which provides a correct basis for proving equivalence of programs, independent from any specific computational model.

Introduction

This paper is about logics for reasoning about programs, in particular for proving equivalence of programs. Following a consolidated tradition in theoretical computer science we identify programs with the closed λ -terms, possibly containing extra constants, corresponding to some features of the programming language under consideration. There are three approaches to proving equivalence of programs:

- The **operational** approach starts from an **operational semantics**, e.g. a partial function mapping every program (i.e. closed term) to its resulting value (if any), which induces a congruence relation on open terms called **operational equivalence** (see e.g. [10]). Then the problem is to prove that two terms are operationally equivalent.
- The **denotational** approach gives an interpretation of the (programming) language in a mathematical structure, the **intended model**. Then the problem is to prove that two terms denote the same object in the intended model.

*Research partially supported by EEC Joint Collaboration Contract # ST2J-0374-C(EDB).

¹Programs are identified with total functions from *values* to *values*.

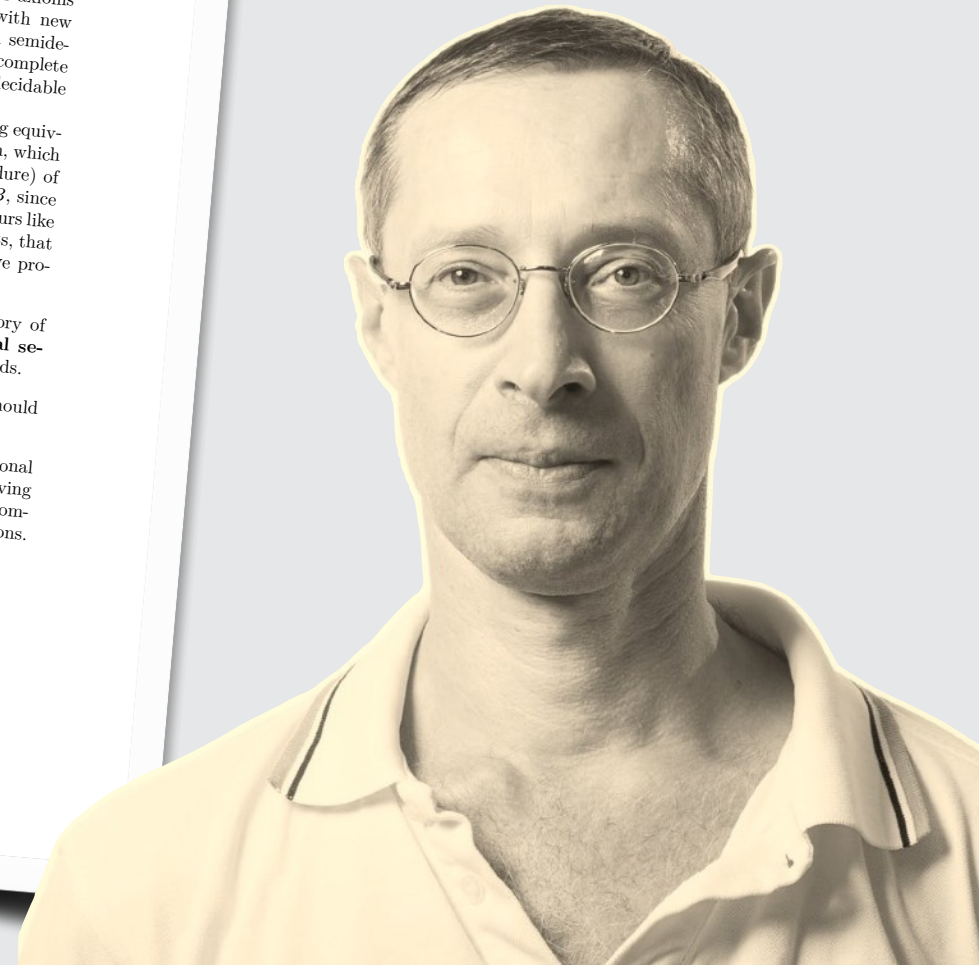
- The **logical** approach gives a class of **possible models** for the language. Then the problem is to prove that two terms denotes the same object in all possible models.

The operational and denotational approaches give only a theory (the operational equivalence \approx and the set Th of formulas valid in the intended model respectively), and they (especially the operational approach) deal with programming languages on a rather case-by-case basis. On the other hand, the logical approach gives a consequence relation \vdash ($Ax \vdash A$ iff the formula A is true in all models of the set of formulas Ax), which can deal with different programming languages (e.g. functional, imperative, non-deterministic) in a rather *uniform* way, by simply changing the set of axioms Ax , and possibly extending the language with new constants. Moreover, the relation \vdash is often semidecidable, so it is possible to give a sound and complete formal system for it, while Th and \approx are semidecidable only in oversimplified cases.

We do not take as a starting point for proving equivalence of programs the theory of $\beta\eta$ -conversion, which identifies the denotation of a program (procedure) of type $A \rightarrow B$ with a total function from A to B , since this identification wipes out completely behaviours like non-termination, non-determinism or side-effects, that can be exhibited by real programs. Instead, we proceed as follows:

1. We take category theory as a general theory of functions and develop on top a **categorical semantics of computations** based on monads.
2. We consider how the categorical semantics should be extended to interpret λ -calculus.

At the end we get a formal system, the computational lambda-calculus (λ_c -calculus for short), for proving **equivalence** of programs, which is sound and complete w.r.t. the categorical semantics of computations.



The initial specification was taken to be **mathematically** more natural

Example 1.3 Non-deterministic computations:

- $T(-)$ is the covariant powerset functor, i.e. $T(A) = \mathcal{P}(A)$ and $T(f)(X)$ is the image of X along f
- $\eta_A(a)$ is the singleton $\{a\}$
- $\mu_A(X)$ is the big union $\cup X$

Computations with side-effects:

- $T(-)$ is the functor $(- \times S)^S$, where S is a nonempty set of stores. Intuitively a computation takes a store and returns a value together with the modified store.
- $\eta_A(a)$ is $(\lambda s: S. \langle a, s \rangle)$
- $\mu_A(f)$ is $(\lambda s: S. \text{eval}(fs))$, i.e. the computation that given a store s , first computes the pair computation-store $\langle f', s' \rangle = fs$ and then returns the pair value-store $\langle a, s'' \rangle = f's'$.

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Example 1.3 Non-deterministic computations:

- $T(-)$ is the power set functor $\mathcal{P}(A)$ and $\eta_A(a)$ is $\{a\}$. There is an alternative description of a monad (see [7]), which is easier to justify computationally.

Definition 1.2 A **Kleisli triple** over \mathcal{C} is a triple $(T, \eta, -^*)$, where $T: \text{Obj}(\mathcal{C}) \rightarrow \text{Obj}(\mathcal{C})$, $\eta_A: A \rightarrow TA$, $f^*: TA \rightarrow TB$ for $f: A \rightarrow TB$ and the following equations hold:

- $\eta_A^* = \text{id}_{TA}$
- $\eta_A; f^* = f$
- $f^*; g^* = (f; g^*)^*$

Every Kleisli triple $(T, \eta, -^*)$ corresponds to a monad (T, η, μ) where $T(f: A \rightarrow B) = (f; \eta_B)^*$ and $\mu_A = \text{id}_{TA}^*$.

In his subsequent work, a **computationally natural** approach was taken

INFORMATION AND COMPUTATION 93, 55-92 (1991)

Notions of Computation and Monads

EUGENIO MOGGI*

Department of Computer Science, University of Edinburgh, Edinburgh EH9 3JZ, UK

The λ -calculus is considered a useful mathematical tool in the study of programming languages, since programs can be identified with λ -terms. However, if one goes further and uses $\beta\eta$ -conversion to prove equivalence of programs, then a gross simplification is introduced (programs are identified with total functions from values to values) that may jeopardise the applicability of theoretical results. In this paper we introduce calculi, based on a categorical semantics for computations, that provide a correct basis for proving equivalence of programs for a wide range of notions of computation. © 1991 Academic Press, Inc.

INTRODUCTION

This paper is about logics for reasoning about programs, in particular for proving equivalence of programs. Following a consolidated tradition in theoretical computer science we identify programs with the closed λ -terms, possibly containing extra constants, corresponding to some features of the programming language under consideration. There are three semantics-based approaches to proving equivalence of programs:

- The *operational* approach starts from an *operational semantics*, e.g., a partial function mapping every program (i.e., closed term) to its resulting value (if any), which induces a congruence relation on open terms called *operational equivalence* (see e.g. Plotkin (1975)). Then the problem is to prove that two terms are operationally equivalent.
- The *denotational* approach gives an interpretation of the (programming) language in a mathematical structure, the *intended model*. Then the problem is to prove that two terms denote the same object in the intended model.
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The operational and denotational approaches give only a theory: the operational equivalence \approx or the set Th of formulas valid in the intended model, respectively. On the other hand, the logical approach gives a conse-

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DEFINITION 1.2 (Manes, 1976). A Kleisli triple over a category \mathcal{C} is a triple $(T, \eta, -^*)$, where $T: \text{Obj}(\mathcal{C}) \rightarrow \text{Obj}(\mathcal{C})$, $\eta_A: A \rightarrow TA$ for $A \in \text{Obj}(\mathcal{C})$, $f^*: TA \rightarrow TB$ for $f: A \rightarrow TB$ and the following equations hold:

- $\eta_A^* = \text{id}_{TA}$
- $\eta_A; f^* = f$ for $f: A \rightarrow TB$
- $f^*; g^* = (f; g^*)^*$ for $f: A \rightarrow TB$ and $g: B \rightarrow TC$.

EXAMPLE 1.4. We go through the notions of computation given in Example 1.1 and show that they are indeed part of suitable Kleisli triples.

- **partiality** $TA = A_\perp (= A + \{\perp\})$
 η_A is the inclusion of A into A_\perp
if $f: A \rightarrow TB$, then $f^*(\perp) = \perp$ and $f^*(a) = f(a)$ (when $a \in A$)
- **nondeterminism** $TA = \mathcal{P}_{\text{fin}}(A)$
 η_A is the singleton map $a \mapsto \{a\}$
if $f: A \rightarrow TB$ and $c \in TA$, then $f^*(c) = \bigcup_{x \in c} f(x)$
- **side-effects** $TA = (A \times S)^S$
 η_A is the map $a \mapsto (\lambda s: S. \langle a, s \rangle)$
if $f: A \rightarrow TB$ and $c \in TA$, then $f^*(c) = \lambda s: S. (\text{let } \langle a, s' \rangle = c(s) \text{ in } f(a)(s'))$

Wadler **transformed** the semantic notion into a **programming construct**

Comprehending Monads

Philip Wadler
University of Glasgow

Abstract

Category theorists invented *monads* in the 1960's to concisely express certain aspects of universal algebra. Functional programmers invented *list comprehensions* in the 1970's to concisely express certain programs involving lists. This paper shows how list comprehensions may be generalised to an arbitrary monad, and how the resulting programming feature can concisely express in a pure functional language some programs that manipulate state, handle exceptions, parse text, or invoke continuations. A new solution to the old problem of destructive array update is also presented. No knowledge of category theory is assumed.

1 Introduction

Is there a way to combine the indulgences of impurity with the blessings of purity?

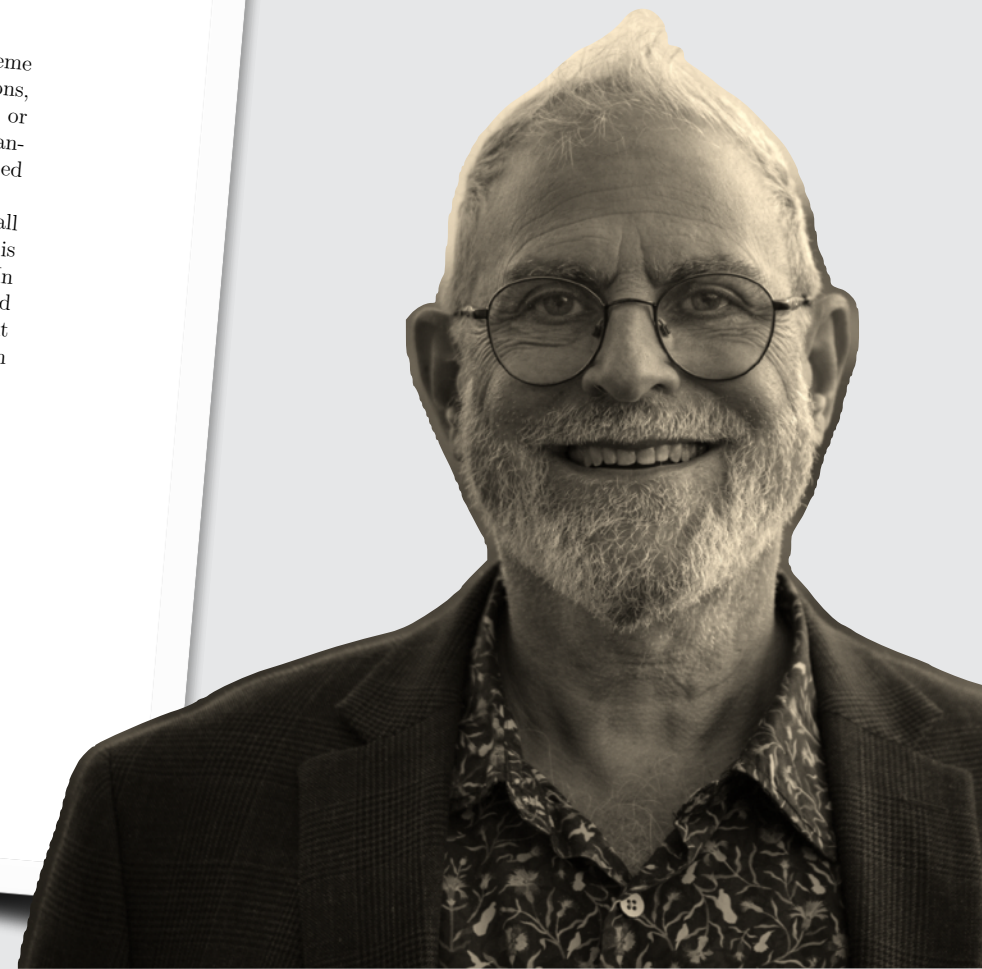
Impure, strict functional languages such as Standard ML [Mil84, HMT88] and Scheme [RC86] support a wide variety of features, such as assigning to state, handling exceptions, and invoking continuations. Pure, lazy functional languages such as Haskell [HPW91] or Miranda¹ [Tur85] eschew such features, because they are incompatible with the advantages of lazy evaluation and equational reasoning, advantages that have been described at length elsewhere [Hug89, BW88].

Purity has its regrets, and all programmers in pure functional languages will recall some moment when an impure feature has tempted them. For instance, if a counter is required to generate unique names, then an assignable variable seems just the ticket. In such cases it is always possible to mimic the required impure feature by straightforward though tedious means. For instance, a counter can be simulated by modifying the relevant functions to accept an additional parameter (the counter's current value) and return an additional result (the counter's updated value).

¹Miranda is a trademark of Research Software Limited.

Author's address: Department of Computing Science, University of Glasgow, G12 8QQ, Scotland. Electronic mail: wadler@cs.glasgow.ac.uk.

This paper appeared in *Mathematical Structures in Computer Science* volume 2, pp. 461–493, 1992; copyright Cambridge University Press. This version corrects a few small errors in the published version. An earlier version appeared in *ACM Conference on Lisp and Functional Programming*, Nice, June 1990.



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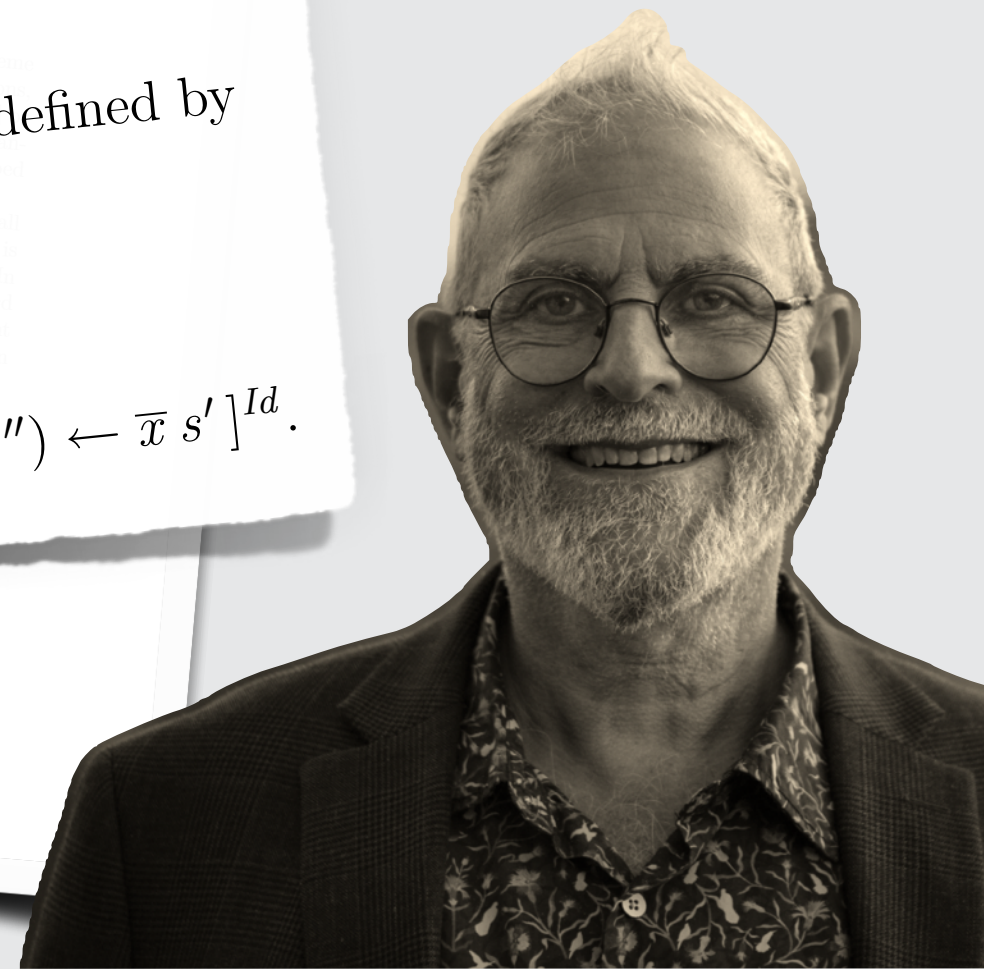
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4.1 State transformers

Fix a type S of states. The monad of state transformers ST is defined by

$$\begin{aligned} \text{type } ST\ x &= S \rightarrow (x, S) \\ \text{map}^{ST}\ f\ \bar{x} &= \lambda s \rightarrow [(f\ x, s') \mid (x, s') \leftarrow \bar{x}\ s]^{Id} \\ \text{unit}^{ST}\ x &= \lambda s \rightarrow (x, s) \\ \text{join}^{ST}\ \bar{\bar{x}} &= \lambda s \rightarrow [(x, s'') \mid (\bar{x}, s') \leftarrow \bar{\bar{x}}\ s, (x, s'') \leftarrow \bar{x}\ s']^{Id}. \end{aligned}$$



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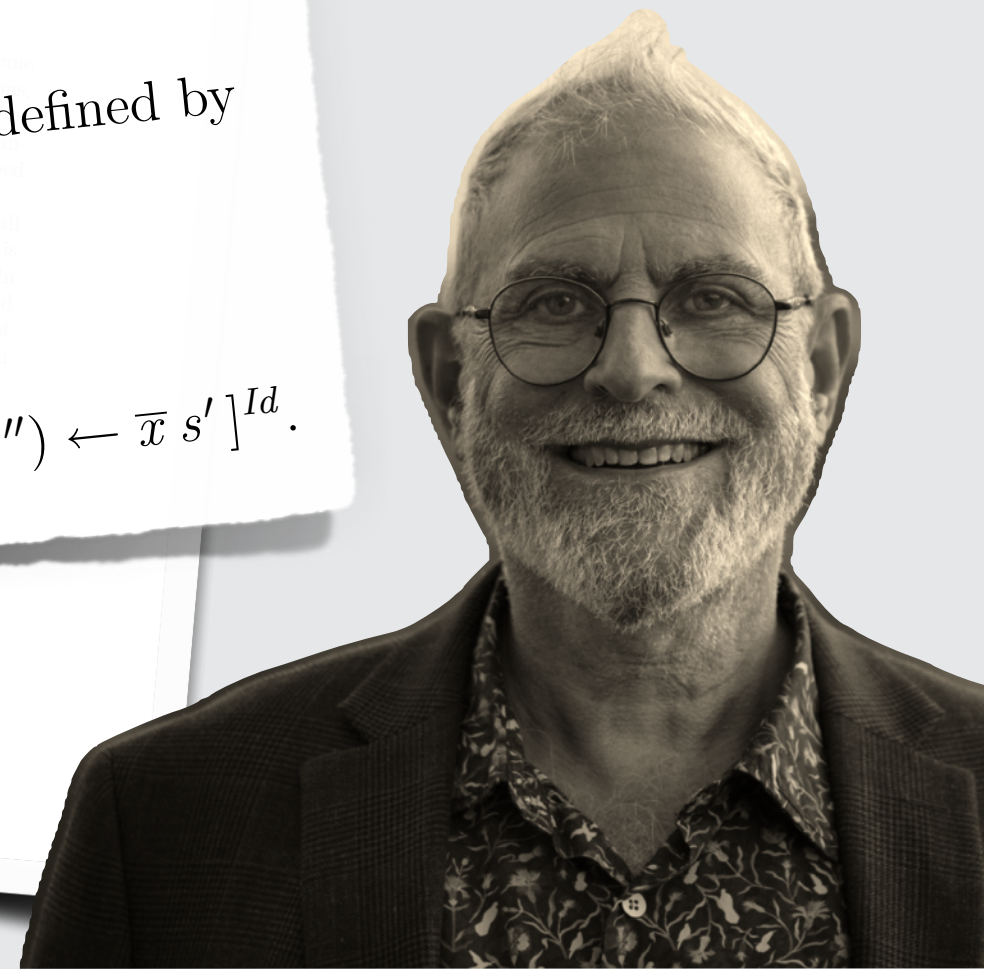
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7.1 Parsers

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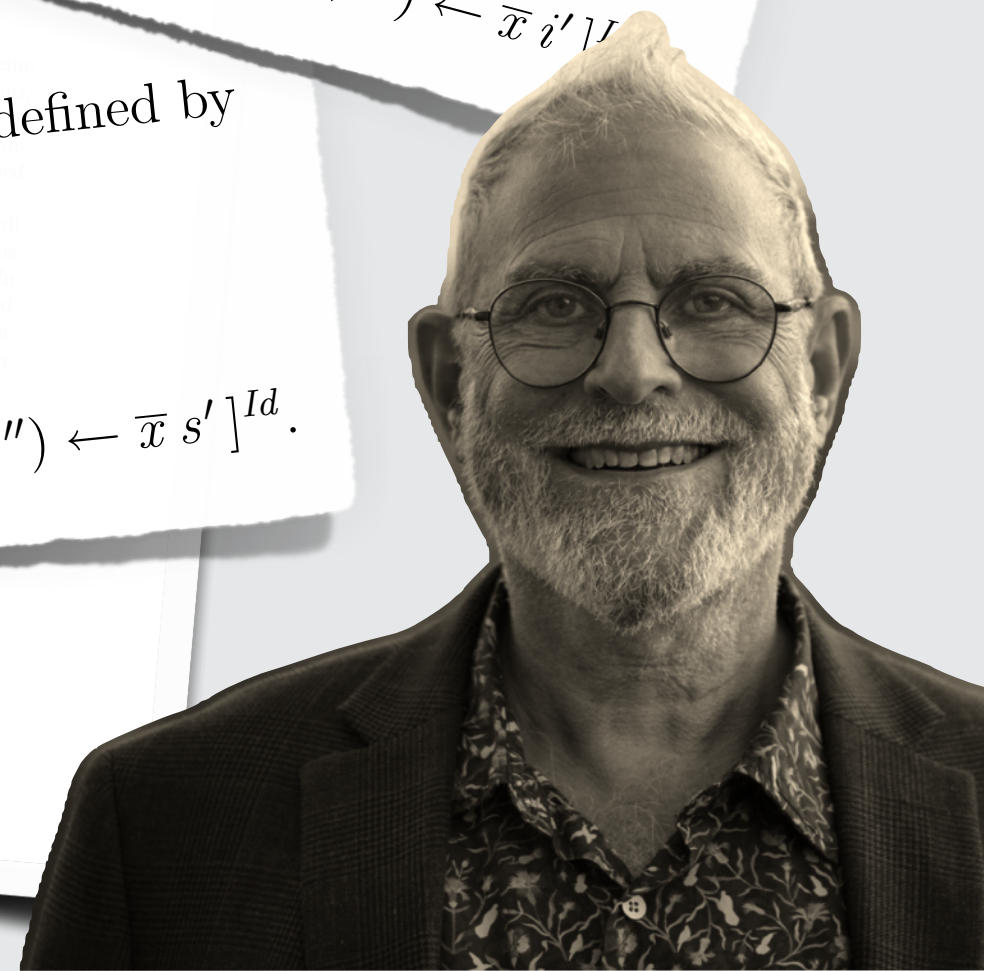
$$\begin{aligned} \text{type Parse } x &= \text{String} \rightarrow \text{List}(x, \text{String}) \\ \text{map}^{\text{Parse}} f \bar{x} &= \lambda i \rightarrow [(f\ x, i') \mid (x, i') \leftarrow \bar{x}\ i]_{\text{List}} \\ \text{unit}^{\text{Parse}} x &= \lambda i \rightarrow [(x, i)]_{\text{List}} \\ \text{join}^{\text{Parse}} \bar{\bar{x}} &= \lambda i \rightarrow [(x, i'') \mid (\bar{x}, i') \leftarrow \bar{\bar{x}}\ i, (x, i'') \leftarrow \bar{x}\ i']_{\text{List}} \end{aligned}$$

1 Introduction

Is there a way to combine the indulgence of impurity with the blessings of purity? Impure, strict functions are useful in many contexts, such as Standard ML (MLM, HMTS) and Scheme. But in pure functional languages, such as Haskell, the lack of state, binding, and side effects makes it difficult to write such functions. This paper presents a way to combine the two.

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An effect is specified with a monad and **additional operations**

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monad

$$TX = \mathcal{P}X$$

$$\eta(x) = \{x\}$$

$$c \gg k = \bigcup_{x \in c} k(x)$$

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effect-specific operations

$$\text{fail} : TX$$

$$\text{fail} = \{\}$$

$$\text{choose} : TX \times TX \rightarrow TX$$

$$\text{choose}(c_1, c_2) = c_1 \cup c_2$$

An effect is specified with **operations** and **equations**

An effect is specified with **operations** and **equations**

operations

fail : 0

choose : 2

An effect is specified with **operations** and **equations**

operations

`fail : 0`

`choose : 2`

equations

`choose (choose $M N$) P = choose M (choose $N P$)`

`choose $M N$ = choose $N M$`

`choose $M M$ = M`

`choose fail M = M = choose M fail`

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operations

$\text{fail} : 0$

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equations

$\text{choose} (\text{choose } M N) P = \text{choose } M (\text{choose } N P)$

$\text{choose } M N = \text{choose } N M$

$\text{choose } M M = M$

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$\text{chs } B (\text{chs } (\text{chs } A C) (\text{chs } B \text{ fail}))$

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$$\begin{aligned} & \text{chs } B (\text{chs } (\text{chs } A C) (\text{chs } B \text{ fail})) \\ &= \text{chs } B (\text{chs } A (\text{chs } C (\text{chs } B \text{ fail}))) \end{aligned}$$

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Exception **handling failed** to be algebraic

exceptions

state

choice

I/O

probability

operations

fail **try**


get set

choose

read write

flip

not
algebraic



Why handling is **not** an **algebraic** operation?

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handling

$$\text{try}(\text{fail}, M) = M$$

$$\text{try}(\text{val } V, M) = \text{val } V$$

Why handling is **not** an **algebraic** operation?

handling

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algebraicity

$$\text{do } x \Leftarrow \text{try}(M_1, M_2) \text{ in } N$$

$$= \text{try}(\text{do } x \Leftarrow M_1 \text{ in } N, \text{do } x \Leftarrow M_2 \text{ in } N)$$

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$$\text{do } x \Leftarrow \text{val } 0 \text{ in } N$$

← failing

$$= \text{do } x \Leftarrow \text{try}(\text{val } 0, \text{val } 1) \text{ in } N$$

$$= \text{try}(\text{do } x \Leftarrow \text{val } 0 \text{ in } N, \text{do } x \Leftarrow \text{val } 1 \text{ in } N)$$

Why handling is **not** an **algebraic** operation?

handling

$$\text{try}(\text{fail}, M) = M$$

$$\text{try}(\text{val } V, M) = \text{val } V$$

algebraicity

$$\begin{aligned} \text{do } x \Leftarrow \text{try}(M_1, M_2) \text{ in } N \\ = \text{try}(\text{do } x \Leftarrow M_1 \text{ in } N, \text{do } x \Leftarrow M_2 \text{ in } N) \end{aligned}$$

$$\text{do } x \Leftarrow \text{val } 0 \text{ in } N$$

← failing

$$= \text{do } x \Leftarrow \text{try}(\text{val } 0, \text{val } 1) \text{ in } N$$

$$= \text{try}(\text{do } x \Leftarrow \text{val } 0 \text{ in } N, \text{do } x \Leftarrow \text{val } 1 \text{ in } N)$$

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Exception handling indicated a **different nature**

Exception handling indicated a **different nature**

On the other hand, for example, the exceptions monad does not support its exception handling operation: only the weaker naturality holds there. This monad is a free algebra functor for an equational theory, viz the one that has a constant for each exception and no equations; however the exception handling operation **is not definable: only the exception raising operations are.** Other standard monads present further difficulties. So while our account of operational semantics is quite general, it certainly does not cover all cases; it remains to be seen if it can be further extended.

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Of the various operations, **handle** is of a different computational character and, although natural, it is not algebraic. Andrzej Filinski (personal communication) describes **handle** as a *deconstructor*, whereas the other operations are *constructors* (of effects). In this paper, we make the notion of constructor precise by identifying it with the notion of *algebraic* operation.

Mathematics was already suggesting **unrevealed constructs**

constructors deconstructors

exceptions fail try

state get set

choice choose

I/O read write

probability flip

Mathematics was already suggesting **unrevealed constructs**

constructors **deconstructors**

exceptions

`fail`

`try`

state

`get set`

choice

`choose`

I/O

`read write`

probability

`flip`



Exception handlers are **homomorphisms** and they **generalise to other effects**

Handlers of Algebraic Effects

Gordon Plotkin * and Matija Pretnar **

Laboratory for Foundations of Computer Science,
School of Informatics, University of Edinburgh, Scotland

Abstract. We present an algebraic treatment of exception handlers and, more generally, introduce handlers for other computational effects representable by an algebraic theory. These include nondeterminism, interactive input/output, concurrency, state, time, and their combinations; in all cases the computation monad is the free-model monad of the theory. Each such handler corresponds to a model of the theory for the effects at hand. The handling construct, which applies a handler to a computation, is based on the one introduced by Benton and Kennedy, and is interpreted using the homomorphism induced by the universal property of the free model. This general construct can be used to describe previously unrelated concepts from both theory and practice.

1 Introduction

In seminal work, Moggi proposed a uniform representation of computational effects by monads [1–3]. The computations that return values from a set X are represented by elements of TX , for a suitable monad T . Examples include exceptions, nondeterminism, interactive input/output, concurrency, state, time, continuations, and combinations thereof. Plotkin and Power later proposed to focus on *algebraic* effects, that is effects that allow a representation by operations and equations [4–6]; the operations give rise to the effects at hand. All of the effects mentioned above are algebraic, with the notable exception of continuations [7], which have to be treated differently (see [8] for initial ideas).

In the algebraic approach the arguments of an operation represent possible computations after an occurrence of an effect. For example, using a binary choice operation $\text{or}: 2$, a nondeterministically chosen boolean is represented by the term $\text{or}(\text{return true}, \text{return false}): F\text{bool}$, where $F\sigma$ stands for the type of computations that return values of type σ . The equations of the theory, for example the ones stating that or is a semi-lattice operation, generate the free-model functor, which is exactly the monad proposed by Moggi to model the corresponding effect [9] (modulo the forgetful functor) and which is used to interpret the type $F\sigma$. The operations are then interpreted by the model structure. When viewed as a family of functions parametric in X , e.g., $\text{or}_X: TX^2 \rightarrow TX$, one obtains a so-called

* Supported by EPSRC grant GR/586371/01 and a Royal Society-Wolfson Award Fellowship.

** Supported by EPSRC grant GR/586371/01.



The Programming Languages Zoo

A potpourri of programming languages

> [home](#)

About the zoo

The Programming Languages Zoo is a collection of miniature programming languages which demonstrates various concepts and techniques used in programming language design and implementation. It is a good starting point for those who would like to implement their own programming language, or just learn how it is done.

The following features are demonstrated:

- >> functional, declarative, object-oriented, and procedural languages
- >> source code parsing with a parser generator
- >> keep track of source code positions
- >> pretty-printing of values
- >> interactive shell (REPL) and non-interactive file processing
- >> untyped, statically and dynamically typed languages
- >> type checking and type inference
- >> subtyping, parametric polymorphism, and other kinds of type systems
- >> eager and lazy evaluation strategies
- >> recursive definitions
- >> exceptions
- >> interpreters and compilers
- >> abstract machine

Installation

See the [installation & compilation instructions](#).

We wanted to **do the same for handlers** as Wadler did for monads

Moggi

*Computational
lambda-calculus
and monads*

1989

Plotkin & P.

*Handlers of
algebraic effects*

2009

Wadler

*Comprehending
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Initial version of Eff had a **Python-like syntax** and was **untyped**

Mathematics and Computation

A blog about mathematics for computers

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← [How eff handles built-in effects](#)

[Programming with effects I: Theory](#) →

Programming with effects II: Introducing eff

🕒 27 September 2010

👤 Matija Pretnar

📁 [Computation](#), [Eff](#), [Guest post](#), [Programming](#), [Software](#), [Tutorial](#)

[**UPDATE 2012-03-08:** since this post was written eff has changed considerably. For updated information, please visit the [eff page](#).]

******This is a second post about the programming language eff. We covered the theory behind it in a [previous post](#). Now we turn to the programming language itself.

Please bear in mind that eff is an academic experiment. It is not meant to take over the world. Yet. We just wanted to show that the theoretical ideas about the algebraic nature of computational effects can be put into practice. Eff has many superficial similarities with Haskell. This is no surprise because there is a precise connection between algebras and monads. The main advantage of eff over Haskell is supposed to be the ease with which computational effects can be combined.

Installation

If you have [Mercurial](#) installed (type hg at command prompt to find out) you can get eff like this:

```
$ hg clone http://hg.andrej.com/eff/ eff
```

Otherwise, you may also download the latest source as a [.zip](#) or [.tar.gz](#), or [visit the repository with your browser](#) for other versions. Eff is

Initial version of Eff had a **Python-like syntax** and was **untyped**

Mathematics and Computation

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Posts

```
effect state x:
  operation get ():
    (lambda s: yield s s)
  operation set s_new:
    (lambda s: yield () s_new)
  return y:
    (lambda s: (s, y))
  finally f: f x
```

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[← The topology of the set of all types](#)

[Programming with Algebraic Effects an... →](#)

Eff 3.0

🕒 08 March 2012

👤 Andrej Bauer

📁 [Eff](#), [News](#)

Matija and I are pleased to announce a new major release of the [eff programming language](#).

In the last year or so eff has matured considerably:

- It now looks and feels like [OCaml](#), so you won't have to learn yet another syntax.
- It has static typing with parametric polymorphism and type inference.
- Eff now clearly separates three basic concepts: effect types, effect instances, and handlers.
- How eff works is explained in our paper on [Programming with Algebraic Effects and Handlers](#).
- We moved the [source code to GitHub](#), so go ahead and fork it!

Comments



Dan Doel

02 April 2012 at 22:05

Mathematics and Computation

A blog

Posts

```
type 'a ref = effect  
  operation get: unit -> 'a  
  operation set: 'a -> unit  
end
```

```
let state r x = handler  
  | r#get () k -> (fun s -> k s s)  
  | r#set s' k -> (fun s -> k () s')  
  | val y -> (fun s -> (y, s))  
  | finally f -> f x
```

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Faculty of Mathematics and Physics, University of Ljubljana, Slovenia

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Eff is a programming language based on the algebraic approach to computational effects, in which effects are viewed as algebraic operations and effect handlers as homomorphisms from free algebras. Eff supports first-class effects and handlers through which we may reason about computational effects, simultaneously combine existing ones, and handle them in novel ways. We give a denotational semantics of Eff and discuss a prototype implementation based on it. Through examples we demonstrate how the standard effects, as handled in Eff, and how Eff supports programming techniques that use various forms of delimited computation, such as backtracking, breadth-first search, iteration, functional, cooperative multi-threading, and others.

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0. Introduction

Eff is a programming language based on the algebraic approach to effects, in which computational effects are modelled as operations of a suitably chosen algebraic theory [17]. Computations with effects are modelled as elements of the free algebra of this theory. Effect handlers are modelled as homomorphisms from the free algebra to the algebra of the effect handlers. Effect handlers are a natural way to model the interaction between a program and its environment. Each algebraic theory gives rise to a monad [1,11], although the operations cannot be reconstructed from it. The algebraic approach therefore seems well-suited to model the interaction between a program and its environment. Philip Wadler once opined [21] that monads as a programming concept would not have been discovered without the same holds for algebraic effects and handlers, we strived to make the paper for the benefit of programmers, instead of mathematicians. The paper is organized as follows. Section 1 describes the syntax of Eff. Section 2 informally introduces constructs used to produce standard computational effects, such as exceptions, state, input and output, and handlers of choice, backtracking, selection functionals, and cooperative multi-threading. We conclude with a summary of the implementation of Eff in freely available at <http://www.eff-lang.org/>.

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Philip Wadler once opined [21] that monads as a programming concept would not have been discovered without their category-theoretic counterparts, but once they were, programmers could live in blissful ignorance of their origin. Because the same holds for algebraic effects and handlers, we streamlined the paper for the benefit of programmers, trusting that connoisseurs will recognize the connections with the underlying mathematical theory.

The paper is organized as follows. Section 1 describes the syntax of *Eff*, Section 2 informally introduces constructs specific to *Eff*, Section 3 is devoted to type checking, in Section 4 we give a domain-theoretic semantics of *Eff*, and in Section 5 we briefly discuss our prototype implementation. The examples in Section 6 demonstrate how effects and handlers can be

Wadler

Comprehending
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0. Introduction

Eff is a programming language based on the algebraic approach to effects, in which computational effects are modelled as operations of a suitably chosen algebraic theory [12]. Concrete computational effects such as input, output, state, exceptions, and nondeterminism, are of this kind. Computations are not algebraic [16] but they turn out to be naturally supported as well. Effect handlers are a related notion [14,18] which encompasses exception handlers, return transformers, trampolines, and many others. These are modelled as homomorphisms between algebras, or more precisely, as transformations between monads. Each algebraic theory gives rise to a monad [1,11], although the operations induced by the universal property of free algebras and handlers have their own virtues, though effects are considered more easily than monads [15], and the interaction of the algebraic approach therefore seems warranted. An experiment in the design of a programming language with category-theoretic constraints, but then they were, programmers could live in blissful ignorance of their origin. Because the same holds for algebraic effects and handlers, we streamlined the paper for the benefit of programmers, trusting that connoisseurs will recognize the connections with the underlying mathematical theory.

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Moving from **mathematics to programming** gave **extra flexibility**

Plotkin & P.



Bauer & P.

Moving from **mathematics to programming** gave **extra flexibility**

Plotkin & P.

$$\frac{x_p:\sigma, x:\beta, z_p:\chi, (z_i:(\alpha_i) \rightarrow \chi)_{i=1}^n \vdash h_{\text{op}}:\chi \quad (\text{op}:\beta; \alpha_1, \dots, \alpha_n \in \Sigma_{\text{eff}})}{\vdash (x_p:\sigma; z_p:\chi). \{ \text{op}_x(z) \mapsto h_{\text{op}} \}_{\text{op} \in \Sigma_{\text{eff}}} : (\sigma; \chi) \rightarrow \chi \text{ handler}}$$

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$$\frac{x_p:\sigma, x:\beta, z_p:\chi, (z_i:(\alpha_i) \rightarrow \chi)_{i=1}^n \vdash h_{op}:\chi \quad (op:\beta; \alpha_1, \dots, \alpha_n \in \Sigma_{\text{eff}})}{\vdash (x_p:\sigma; z_p:\chi). \{op_x(z) \mapsto h_{op}\}_{op \in \Sigma_{\text{eff}}} : (\sigma; \chi) \rightarrow \chi \text{ handler}}$$

$e ::= x \mid n \mid b \mid \text{true} \mid \text{false} \mid () \mid (e_1, e_2) \mid$
 $\text{Left } e \mid \text{Right } e \mid \text{fun } x:A \mapsto c \mid e \# op \mid h,$

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Notion of models **got absorbed** in homomorphisms

Plotkin & P.



Bauer & P.

Notion of models got absorbed in homomorphisms

Plotkin & P.

A handler

$$h = \text{handler } (e_i \# \text{op}_i x k \mapsto c_i)_i \mid \text{val } x \mapsto c_v \mid \text{finally } x \mapsto c_f$$

may be applied to a computation c with the handling construct

with h handle c ,

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Benton and Kennedy noted a few issues about the syntax of their construct when used for programming [13]. It is not obvious that t is handled whereas t' is not, especially when t' is large and the handler is obscured. An alternative they propose is $\text{try } x \Leftarrow t \text{ unless } \{e_1 \Rightarrow t_1 \mid \dots \mid e_n \Rightarrow t_n\}_i \text{ in } t'$, but then it is not obvious that x is bound in t' , but not in the handler. The syntax of our construct **$\text{try } t \text{ with } H(u; t) \text{ as } x \text{ in } t'$** addresses those issues and clarifies the order of evaluation: after t is handled with H , its results are bound to x and used in t' .

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Equations disappeared

Plotkin & P.



Bauer & P.

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ensuring correctness

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ensuring correctness

~~programmer
writes and uses
handlers~~

language designer
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programmer
uses them

maximum result

operations

or : 2

handlers

$H_{\max} = \{ \text{or}(x_1, x_2) \rightarrow \max(x_1, x_2) \}$

try or(or(3, 2), 5) with $H_{\max} = 5$

$H_{\text{sum}} = \{ \text{or}(x_1, x_2) \rightarrow x_1 + x_2 \}$

~~try or(3, 3) with $H_{\text{sum}} = 6$~~

try 3 with $H_{\text{sum}} = 3$

Bauer & P.

Equations disappeared

Plotkin & P.

framework [15, 11]. Section 3, describes (base) values and the algebraic theory of effects. A natural need for two languages arises: one to describe handlers, given in Section 4, and one where they are used to handle computations, given in Section 5. The second parts of these sections give the relevant denotational semantics; readers may wish to see Section 6, where

ensuring correctness

~~programmer
writes and uses
handlers~~

language designer
writes handlers

programmer
uses them

maximum result

operations

or : 2

handlers

$H_{\max} = \{ \text{or}(x_1, x_2) \rightarrow \max(x_1, x_2) \}$

try or(or(3, 2), 5) with $H_{\max} = 5$

$H_{\text{sum}} = \{ \text{or}(x_1, x_2) \rightarrow x_1 + x_2 \}$

~~try or(3, 3) with $H_{\text{sum}} = 6$~~

try 3 with $H_{\text{sum}} = 3$

Bauer & P.

Shallow handlers were visible only when looking operationally



Handlers in Action

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Abstract

Plotkin and Pretnar's handlers for algebraic effects occupy a sweet spot in the design space of abstractions for effectful computation. By separating effect signatures from their implementation, algebraic effects provide a high degree of modularity, allowing programmers to express effectful programs independently of the concrete interpretation of their effects. A handler is an interpretation of the effects of an algebraic computation. The handler abstraction adapts well to multiple settings: pure or impure, strict or lazy, static types or dynamic types.

This is a position paper whose main aim is to popularise the handler abstraction. We give a gentle introduction to its use, a collection of illustrative examples, and a straightforward operational semantics. We describe our Haskell implementation of handlers in detail, outline the ideas behind our OCaml, SML, and Racket implementations, and present experimental results comparing handlers with existing code.

Categories and Subject Descriptors D.1.1 [Applicative (Functional) Programming]; D.3.1 [Formal Definitions and Theory]; D.3.2 [Language Classifications]: Applicative (functional) languages; D.3.3 [Language Constructs and Features]; F.3.2 [Semantics of Programming Languages]: Operational semantics

Keywords algebraic effects; effect handlers; effect typing; monads; continuations; Haskell; modularity

1. Introduction

Monads have proven remarkably successful in their application over effectful computations [4, 30]. They provide a programming language primitive via which one can express a computation principle: program to an interface, run on an implementation.

Modular programs are constructed by composing building blocks. This is modular programming. In the presence of an abstract interface, we instantiate a computation independently instantiated with respect to the interface. This is modular instantiation.

The monadic approach to effectful computation creates implementation rather than interface. For instance, in Haskell

```
newtype State s a = State { runState :: s -> (a, s) }
instance Monad (State s) where
  return x = State (\s -> (x, s))
  m >=> f = State (\s -> let (x, s') = runState m s in
                        runState (f x) s')
```

This definition says nothing about the intended use of *State s a* as the type of computations that read and write state. Worse, it breaks abstraction as consumers of state are exposed to its concrete implementation as a function of type $s \rightarrow (a, s)$. We can of course define the natural *get* and *put* operations on state, but their implementations are fixed.

Jones [18] advocates modular abstraction for monads in Haskell using type classes. For instance, we can define the following interface to abstract state computation¹:

```
class Monad m => MonadState s m | m -> s where
  get :: m s
  put :: s -> m ()
```

The *MonadState* interface can be smoothly combined with other interfaces, taking advantage of Haskell's type class mechanism to represent type-level sets of effects.

Monad transformers [25] provide a form of modular instantiation for abstract monadic computations. For instance, state can be handled in the presence of other effects by incorporating a monad transformer within a monad transformer stack.

A fundamental problem with monad transformers is that a particular abstract effect is instantiated in a concrete monad. This becomes concrete, and it becomes concrete through the stack. Tamara Rasmussen's research area [16, 17, 38] has been concerned with this problem.

One can solve this problem by adding a monad transformer to the stack. This is modular abstraction. It is a form of modular abstraction that composes abstract operations with concrete operations.

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¹Library [12].

Shallow handlers were visible only when looking **operationally**

Handlers in Action

Ohad Kammar

Another possible behaviour is for the continuation to return an unhandled computation, which must then be handled explicitly. We call such handlers *shallow handlers* because each handler only handles one step of a computation, in contrast to Plotkin and Pretnar's *deep handlers*. Shallow handlers are to deep handlers as case analysis is to a fold on an algebraic data type.

Keywords algebraic effects; effect handlers; effect typing; monads; continuations; Haskell; modularity

1. Introduction

Monads have proven remarkably successful in their application over effectful computations [4, 30]. The monadic programming language primitive via which the monadic principle is applied is the *monadic primitive*: program to an *monadic primitive*.

Modular programs are composed of building blocks. This is modular programming. Given a composite interface, we instantiate it independently. This is modular instantiation.

The monadic approach to
crete implementation rather
For instance, in Haskell

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A fundamental problem with monad transform...

comes concrete, and it becomes through the stack. Tamir research area [16, 138]

Research area [16, 17, 18]
down monad
poly adding
modular abs

by adding
modular abstr
act operati
pose

pose
ratio

alg... e e ch
er hander in ole

Library [12].



Shallow handlers were visible only when looking operationally

Handlers in Action

Ohad Kammar

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1. Introduction

Monads have proven remarkably successful in representing computation over effectful computations [4, 30]. The monad programming language primitive via the monad monad principle: program to an instance of a monad.

Modular programs are constructed from modular building blocks. This is modular programming. Given an abstract interface, we instantiate a modular program independently instantiated with a concrete implementation. This is modular instantiation.

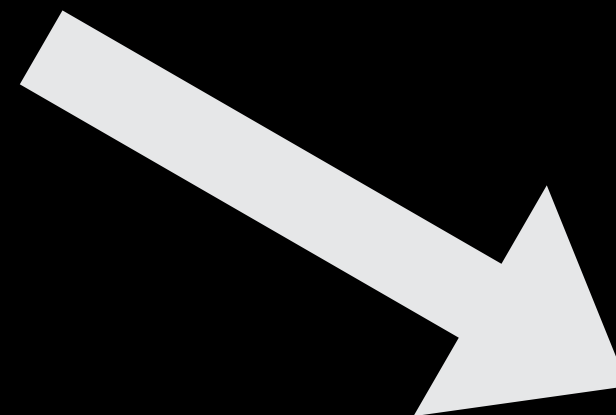
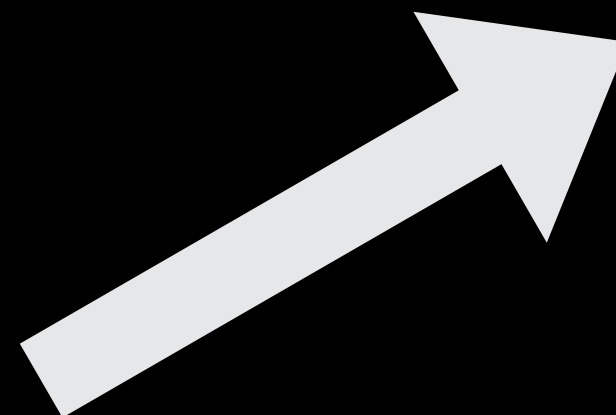
The monadic approach to modular programming is a concrete implementation rather than an abstract interface. For instance, in Haskell

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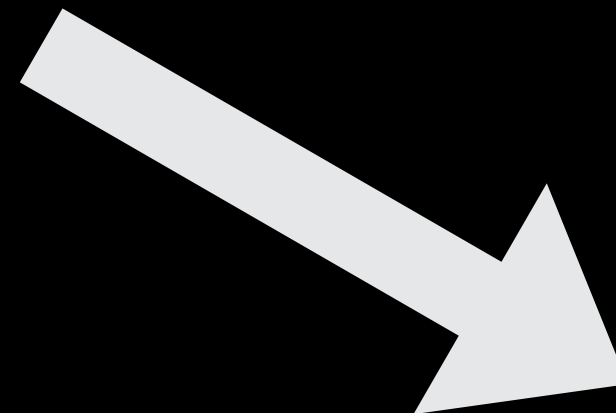
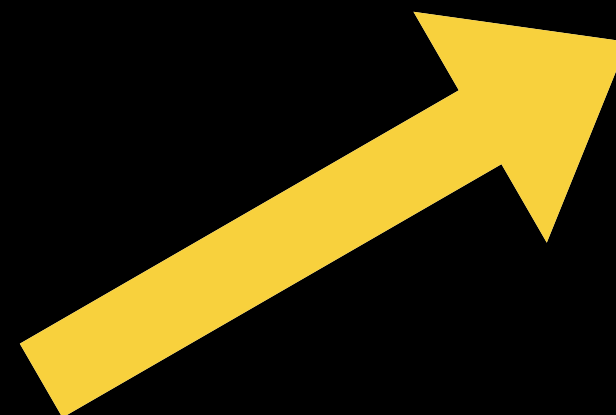


HANDLERS





HANDLERS



Equations not only describe effects, but entail additional laws

Algebraic Foundations for Effect-Dependent Optimisations

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Abstract

We present a general theory of Gifford-style type and effect annotations, where effect annotations are sets of effects. Generality is achieved by recourse to the theory of algebraic effects, a development of Moggi's monadic theory of computational effects that emphasises the operations causing the effects at hand and their equational theory. The key observation is that annotation effects can be identified with operation symbols.

We develop an annotated version of Levy's Call-by-Push-Value language with a kind of computations for every effect set; it can be thought of as a sequential, annotated intermediate language. We develop a range of validated optimisations (i.e., equivalences), generalising many existing ones and adding new ones. We classify these optimisations as structural, algebraic, or abstract: structural optimisations always hold; algebraic ones depend on the effect theory at hand; and abstract ones depend on the global nature of their validity (we give modularly-checkable sufficient conditions for their validity).

Categories and Subject Descriptors D.3.4 [Processors]: Compilers; Optimization; F.3.1 [Specifying and Verifying and Reasoning about Programs]: Logics of programs; F.3.2 [Semantics of Programming Languages]: Algebraic approaches to semantics; Denotational semantics; Program analysis; F.3.3 [Studies of Program Constructs]: Type structure

General Terms Languages, Theory.

Keywords Call-by-Push-Value, algebraic theory of effects, code transformations, compiler optimisations, computational effects, denotational semantics, domain theory, inequational logic, relevant and affine monads, sum and tensor, type and effect systems, universal algebra.

1. Introduction

In Gifford-style type and effect analysis [27], each term of a programming language is assigned a type and an effect set. The type describes the values the term may evaluate to; the effect set describes the effects the term may cause during its computation, such as memory assignment, exception raising, or I/O.

For example, consider the following term M :

$\text{if true then } x := 1 \text{ else } x := \text{deref}(y)$

It has unit type 1 as its sole purpose is to cause side effects; it has effect set $\{\text{update}, \text{lookup}\}$, as it might cause memory updates or look-ups. Type and effect systems commonly convey this information via a type and effect judgement:

$x : \text{Loc}, y : \text{Loc} \vdash M : 1 ! \{\text{update}, \text{lookup}\}$

The information gathered by such effect analyses can be used to guarantee implementation correctness¹, to prove authenticity properties [15], to aid resource management [44], or to optimise code using transformations. We focus on the last of these. As an example, purely functional code can be executed out of order:

$x \leftarrow M_1; y \leftarrow M_2; N \quad = \quad y \leftarrow M_2; x \leftarrow M_1; N$

This reordering holds more generally, if the terms M_1 and M_2 have non-interfering effects. Such transformations are commonly used in optimising compilers. They are traditionally called *optimisations*, even if neither side is always the more optimal.

In a sequence of papers, Benton et al. [4–8] prove soundness of such optimisations for increasingly complex sets of effects. However, any change in the language requires a complete reformulation of its semantics and so of the soundness proofs, even though the essential reasons for the validity of the optimisations remain the same. Thus, this approach is not robust, as small language changes cause global theory changes.

A possible way to obtain robustness is to study effect systems in general. One would hope for a modular approach, seeking to isolate those parts of the theory that change under small language changes, and then recombining them with the unchanging parts. Such a theory may not only be important for compiler optimisations in big, stable languages. It can also be used for effect-dependent equational reasoning. This use may be especially helpful in the case of small, domain-specific languages, as optimising compilers are hardly ever designed for them and their diversity necessitates proceeding modularly.

The only available general work on effect systems is that of Marino and Millstein [28]. They devise a call-by-value language with recursion and references. Their methodology does not account for effect-dependence.

Fortunately, Wadler and Thiemann [46, 47] made an important connection with the monadic theory of computational effects. They translated judgements $\Gamma \vdash M : A ! \varepsilon$ in a region analysis calculus to judgements $\Gamma' \vdash M' : T_\varepsilon A$ in a multi-monadic calculus. The latter calculus has an operational semantics, and the existence of a corresponding general monadic denotational semantics in which T_ε would denote a monad corresponding to ε , and in which the partial order of effect sets and in

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¹E. Cooper, S. Lindley, P. Wadler, and J. Yallop. <http://groups.inf.ed.ac.uk/links>.



Dropping equations due to handlers **weakens the results** of the logic

operations

$\text{fail} : 0$

$\text{choose} : 2$

equations

$\text{choose} (\text{choose } M N) P = \text{choose } M (\text{choose } N P)$

$\text{choose } M N = \text{choose } N M$

$\text{choose } M M = M$

$\text{choose fail } M = M = \text{choose } M \text{ fail}$

algebraicity

$\text{do } x \Leftarrow (\text{choose } M N) \text{ in } P = \text{choose} (\text{do } x \Leftarrow M \text{ in } P) (\text{do } x \Leftarrow N \text{ in } P)$

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$\text{fail} : 0$
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equations

$\text{choose} (\text{choose } M N) P = \text{choose } M (\text{choose } N P)$
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 $\text{choose } M M = M$
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nondeterministic laws

$\text{choose} (\text{do } x \Leftarrow M \text{ in } N) (\text{do } x \Leftarrow M \text{ in } P) = \text{do } x \Leftarrow M \text{ in } (\text{choose } N P)$
 $\text{do } x \Leftarrow M \text{ in } (\text{do } y \Leftarrow N \text{ in } P) = \text{do } y \Leftarrow N \text{ in } (\text{do } x \Leftarrow M \text{ in } P)$

Dropping equations due to handlers **weakens the results** of the logic

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$$\text{do } x \Leftarrow (\text{choose } M N) \text{ in } P = \text{choose } (\text{do } x \Leftarrow M \text{ in } P) (\text{do } x \Leftarrow N \text{ in } P)$$

nondeterministic laws

$$\begin{aligned} \text{choose } (\text{do } x \Leftarrow M \text{ in } N) (\text{do } x \Leftarrow M \text{ in } P) &= \text{do } x \Leftarrow M \text{ in } (\text{choose } N P) \\ \text{do } x \Leftarrow M \text{ in } (\text{do } y \Leftarrow N \text{ in } P) &= \text{do } y \Leftarrow N \text{ in } (\text{do } x \Leftarrow M \text{ in } P) \end{aligned}$$

Dropping equations due to handlers **weakens the results** of the logic

operations

$\text{fail} : 0$

$\text{choose} : 2$

algebraicity

$\text{do } x \Leftarrow (\text{choose } MN) \text{ in } P = \text{choose } (\text{do } x \Leftarrow M \text{ in } P) (\text{do } x \Leftarrow N \text{ in } P)$

Certain laws can be reconstructed **under a particular handler**

AN EFFECT SYSTEM FOR ALGEBRAIC EFFECTS AND HANDLERS

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ABSTRACT. We present an effect system for *core Eff*, a simplified variant of *Eff*, which is an ML-style programming language with first-class algebraic effects and handlers. We define an expressive effect system and prove safety of operational semantics with respect to it. Then we give a domain-theoretic denotational semantics of *core Eff*, using Pitts's theory of minimal invariant relations, and prove it adequate. We use this fact to develop tools for finding useful contextual equivalences, including an induction principle. To demonstrate their usefulness, we use these tools to derive the usual equations for mutable state, including a general commutativity law for computations using non-interfering references. We have formalized the effect system, the operational semantics, and the safety theorem in Twelf.

1. INTRODUCTION

An *effect system* supplements a traditional type system for a programming language with information about which computational effects may, will, or will not happen when a piece of code is executed. A well designed and solidly implemented effect system helps programmers understand source code, find mistakes, as well as safely rearrange, optimize, and parallelize code [11, 8]. As many before us [11, 24, 25, 7] we take on the task of striking just the right balance between simplicity and expressiveness by devising an effect system for *Eff* [2], an ML-style programming language with first-class algebraic effects [17, 15] and handlers [19].

Our effect system is *descriptive* in the sense that it provides information about possible computational effects but it does not prescribe them. In contrast, Haskell's monads *prescribe* the possible effects by wrapping types into computational monads. In the implementation we envision effect inference which never fails, although in some cases it may be uninformative. Of course, typing errors are still errors.

An important feature of our effect system is *non-monotonicity*: it detects the fact that a handler removes some effects. For instance, a piece of code which uses mutable state is determined to actually be pure when wrapped by a handler that handles away lookups and updates.

1998 ACM Subject Classification: D3.3, F3.2, F3.3.

Key words and phrases: algebraic effects, effect handlers, effect system.
A preliminary version of this work was presented at CALCO 2013, see [3].

LOGICAL METHODS
IN COMPUTER SCIENCE

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Certain laws can be reconstructed **under a particular handler**

We demonstrate the technique for mutable state. Let $h = \text{state}_\iota$ and abbreviate
as $\mathcal{H}[c, e]$. Straightforward calculations give us the equivalences

$$\begin{aligned}\text{let } f &= (\text{with } h \text{ handle } c) \text{ in } f e \\ \mathcal{H}[(\iota\#\text{lookup } ()) (y.c)), e] &\equiv \mathcal{H}[c[e/y], e] \\ \mathcal{H}[(\iota\#\text{update } e' (-.c)), e] &\equiv \mathcal{H}[c, e'] \\ \mathcal{H}[\text{val } e', e] &\equiv \text{val } e',\end{aligned}$$

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LOGICAL METHODS
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$$\begin{aligned}\mathcal{H}[\iota\#\text{lookup } () (y.\iota\#\text{update } y (-.c)), e] &\equiv \mathcal{H}[c, e] \\ \mathcal{H}[\iota\#\text{lookup } () (y.\iota\#\text{lookup } () (z.c)), e] &\equiv \mathcal{H}[\iota\#\text{lookup } () (y.c[y/z]), e] \\ \mathcal{H}[\iota\#\text{update } e (-.\iota\#\text{update } e' (-.c)), e] &\equiv \mathcal{H}[\iota\#\text{update } e' (-.c), e] \\ \mathcal{H}[\iota\#\text{update } e (-.\iota\#\text{lookup } () (y.c)), e] &\equiv \mathcal{H}[\iota\#\text{update } e (-.c[e/y]), e]\end{aligned}$$

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The technique can and **has to be repeated** for any concrete handler

The technique can and **has to be repeated** for any concrete handler

$$\mathcal{H}_{\max}[M] = \text{with } H_{\max} \text{ handle } M$$

$$\mathcal{H}_{\max}[\text{choose } (\text{do } x \Leftarrow M \text{ in } N) (\text{do } x \Leftarrow M \text{ in } P)] = \mathcal{H}_{\max}[\text{do } x \Leftarrow M \text{ in } (\text{choose } NP)]$$

$$\mathcal{H}_{\max}[\text{do } x \Leftarrow M \text{ in } (\text{do } y \Leftarrow N \text{ in } P)] = \mathcal{H}_{\max}[\text{do } y \Leftarrow N \text{ in } (\text{do } x \Leftarrow M \text{ in } P)]$$

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$$\mathcal{H}_{\text{sum}}[M] = \text{with } H_{\text{sum}} \text{ handle } M$$

$$\mathcal{H}_{\text{sum}}[\text{choose } (\text{do } x \Leftarrow M \text{ in } N) (\text{do } x \Leftarrow M \text{ in } P)] = \mathcal{H}_{\text{sum}}[\text{do } x \Leftarrow M \text{ in } (\text{choose } NP)]$$

$$\mathcal{H}_{\text{sum}}[\text{do } x \Leftarrow M \text{ in } (\text{do } y \Leftarrow N \text{ in } P)] = \mathcal{H}_{\text{sum}}[\text{do } y \Leftarrow N \text{ in } (\text{do } x \Leftarrow M \text{ in } P)]$$

The technique can and **has to be repeated** for any concrete handler

$$\mathcal{H}_{\max}[M] = \text{with } H_{\max} \text{ handle } M$$

$$\mathcal{H}_{\max}[\text{choose } (\text{do } x \Leftarrow M \text{ in } N) (\text{do } x \Leftarrow M \text{ in } P)] = \mathcal{H}_{\max}[\text{do } x \Leftarrow M \text{ in } (\text{choose } NP)]$$

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$$\mathcal{H}_{\text{sum}}[M] = \text{with } H_{\text{sum}} \text{ handle } M$$

$$\mathcal{H}_{\text{sum}}[\text{choose } (\text{do } x \Leftarrow M \text{ in } N) (\text{do } x \Leftarrow M \text{ in } P)] = \mathcal{H}_{\text{sum}}[\text{do } x \Leftarrow M \text{ in } (\text{choose } NP)]$$

$$\mathcal{H}_{\text{sum}}[\text{do } x \Leftarrow M \text{ in } (\text{do } y \Leftarrow N \text{ in } P)] = \mathcal{H}_{\text{sum}}[\text{do } y \Leftarrow N \text{ in } (\text{do } x \Leftarrow M \text{ in } P)]$$

$$\mathcal{H}_{\text{list}}[M] = \text{with } H_{\text{list}} \text{ handle } M$$

$$\mathcal{H}_{\text{list}}[\text{choose } (\text{do } x \Leftarrow M \text{ in } N) (\text{do } x \Leftarrow M \text{ in } P)] = \mathcal{H}_{\text{list}}[\text{do } x \Leftarrow M \text{ in } (\text{choose } NP)]$$

$$\mathcal{H}_{\text{list}}[\text{do } x \Leftarrow M \text{ in } (\text{do } y \Leftarrow N \text{ in } P)] \neq \mathcal{H}_{\text{list}}[\text{do } y \Leftarrow N \text{ in } (\text{do } x \Leftarrow M \text{ in } P)]$$

Different handlers satisfy **varying equations**

	left		right		
	max	sum	list	swap	
assoc	✓	✓	✓	✓	
comm	✓	✓	✗	✗	✓
idem	✓	✗	✗	✓	✓
unit	✓	✓	✓	✗	✓

Could equations be tracked with an **effect system**?

Could equations be tracked with an **effect system**?

$$\llbracket \sigma ! \varphi \rrbracket = T_{\varphi} \llbracket \sigma \rrbracket$$

$$\llbracket \sigma ! \varphi / \mathcal{E} \rrbracket = T_{\varphi} \llbracket \sigma \rrbracket / \sim_{\mathcal{E}}$$

Could equations be tracked with an **effect system**?

$$\llbracket \sigma ! \varphi \rrbracket = T_{\varphi} \llbracket \sigma \rrbracket$$

(absolutely) free model

$$\llbracket \sigma ! \varphi / \mathcal{E} \rrbracket = T_{\varphi} \llbracket \sigma \rrbracket / \sim_{\mathcal{E}}$$

Could equations be tracked with an **effect system**?

$$\llbracket \sigma ! \varphi \rrbracket = T_{\varphi} \llbracket \sigma \rrbracket$$

(absolutely) free model

$$\llbracket \sigma ! \varphi / \mathcal{E} \rrbracket = T_{\varphi} \llbracket \sigma \rrbracket / \sim_{\mathcal{E}}$$

equivalence
relation

Could equations be tracked with an **effect system**?

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Previous reasoning can be factored into **two parts**

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handlers respect equations

$$H_{\max} : \text{int}!\{\text{choose}, \text{fail}\} / \overbrace{\{\text{assoc}, \text{comm}, \text{idem}, \text{unit}\}}^{\mathcal{E}} \Rightarrow \text{int}!\emptyset/\emptyset$$

$$H_{\text{sum}} : \text{int}!\{\text{choose}, \text{fail}\} / \mathcal{E} \Rightarrow \text{int}!\emptyset/\emptyset$$

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$$H_{\text{swap}} : \tau!\{\text{choose}, \text{fail}\} / \mathcal{E} \Rightarrow \tau!\{\text{choose}, \text{fail}\} / \mathcal{E}$$

equations imply properties

$$\text{choose}(\text{do } x \Leftarrow M \text{ in } N)(\text{do } x \Leftarrow M \text{ in } P) =_{\mathcal{E}} \text{do } x \Leftarrow M \text{ in } (\text{choose } NP)$$

$$\text{do } x \Leftarrow M \text{ in } (\text{do } y \Leftarrow N \text{ in } P) =_{\mathcal{E}} \text{do } y \Leftarrow N \text{ in } (\text{do } x \Leftarrow M \text{ in } P)$$

Typing rules for **monadic constructs**

$$\frac{\Gamma \vdash V : \sigma}{\Gamma \vdash \text{val } V : \sigma! \varphi / \mathcal{E}}$$

$$\frac{\Gamma \vdash M : \sigma! \varphi / \mathcal{E} \quad \Gamma, x : \sigma \vdash N : \tau! \varphi / \mathcal{E}}{\Gamma \vdash \text{do } x \Leftarrow M \text{ in } P : \tau! \varphi / \mathcal{E}}$$

$$\frac{\Gamma \vdash V : \sigma \quad (F : \sigma \rightarrow \tau) \in \varphi}{\Gamma \vdash \text{perform } F V : \tau! \varphi / \mathcal{E}}$$

Handling and subsumption typing rules

$$\frac{\Gamma \vdash H : \sigma! \varphi / \mathcal{E} \Rightarrow \tau! \varphi' / \mathcal{E}' \quad \Gamma \vdash M : \sigma! \varphi / \mathcal{E}}{\Gamma \vdash \text{with } H \text{ handle } M : \tau! \varphi' / \mathcal{E}'}$$

$$\frac{\Gamma \vdash M : \sigma! \varphi / \mathcal{E} \quad \sigma <: \sigma' \quad \varphi \subseteq \varphi' \quad \mathcal{E}' \models \mathcal{E}}{\Gamma \vdash M : \sigma'! \varphi' / \mathcal{E}'}$$

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Handler typing rule and **instantiation** of theory **equations**

$$\frac{\begin{array}{c} \Gamma \vdash H:\sigma!\varphi \rightsquigarrow \tau!\varphi'/\mathcal{E}' \\ \left[\Gamma \vdash H[T_1] = H[T_2]:\tau!\varphi'/\mathcal{E}' \right]_{(T_1=T_2) \in \mathcal{E}} \end{array}}{\Gamma \vdash H : \sigma!\varphi/\mathcal{E} \Rightarrow \tau!\varphi'/\mathcal{E}'}$$

$$\frac{\begin{array}{c} (T_1 = T_2) \in \mathcal{E} \quad [\Gamma \vdash M_i : \sigma!\varphi/\mathcal{E}]_i \end{array}}{\Gamma \vdash T_1(M_1, \dots, M_n) = T_2(M_1, \dots, M_n) : \sigma!\varphi/\mathcal{E}}$$

Handler typing rule and **instantiation** of theory **equations**

well-typed
handling
clauses



$$\Gamma \vdash H : \sigma ! \varphi \rightsquigarrow \tau ! \varphi' / \mathcal{E}'$$

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respecting
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$$\Gamma \vdash T_1(M_1, \dots, M_n) = T_2(M_1, \dots, M_n) : \sigma ! \varphi / \mathcal{E}$$

This work has only **partly** been **put into practice**

Under consideration for publication in J. Functional Programming

1

Local Algebraic Effect Theories

Žiga Lukšič and Matija Pretnar*

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Abstract

Algebraic effects are computational effects that can be described with a set of basic operations and equations between them. As many interesting effect handlers do not respect these equations, most approaches assume a trivial theory, sacrificing both reasoning power and safety.

We present an alternative approach where the type system tracks equations that are observed in subparts of the program, yielding a sound and flexible logic, and paving a way for practical optimizations and reasoning tools.

Algebraic effects are computational effects that can be described by a *signature* of primitive operations and a collection of equations between them (Plotkin & Power, 2001; Plotkin & Power, 2003), while algebraic effect *handlers* are a generalization of exception handlers to arbitrary algebraic effects (Plotkin & Pretnar, 2009; Plotkin & Pretnar, 2013). Even though the early work considered only handlers that respect equations of the effect theory, a considerable amount of useful handlers did not, and the restriction was dropped in most — though not all (Ahman, 2018) — of the later work on handlers (Kammar *et al.*, 2013; Bauer & Pretnar, 2015; Leijen, 2017; Biernacki *et al.*, 2018), resulting in a weaker reasoning logic and imprecise specifications.

Our aim is to rectify this by reintroducing effect theories into the type system, tracking equations observed in parts of a program. On one hand, the induced logic allows us to rewrite computations into equivalent ones with respect to the effect theory, while on the other hand, the type system enforces that handlers preserve equivalences, further specifying their behaviour. After an informal overview in Section 1, we proceed as follows:

- The syntax of the working language, its operational semantics, and the typing rules are given in Section 2.
- Determining if a handler respects an effect theory is in general undecidable (Plotkin & Pretnar, 2013), so there is no canonical way of defining such a judgement. Therefore, the typing rules are given parametric to a reasoning logic, and in Section 3, we present some of the more interesting choices.
- Since the definition of typing judgements is intertwined with a reasoning logic, we must be careful when defining the denotation of types and terms. Thus, in Section 4, we first introduce a set-based denotational semantics that disregards effect theories and prove the expected meta-theoretic properties.

* This material is based upon work supported by the Air Force Office of Scientific Research under award number FA9550-17-1-0326.



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Local Δ'

Algebraic Effect Theories

```
theory eqn_assoc for {choice} is
{ . ; z1 : unit -> *, z2 : unit -> *, z3 : unit -> * |-
  Choice(); b.
    if b then z1 ()
    else Choice(); b'. if b' then z2 () else z3 () )
~
Choice(); b.
  if b then Choice(); b'. if b' then z1 () else z2 ()
else z3 () }

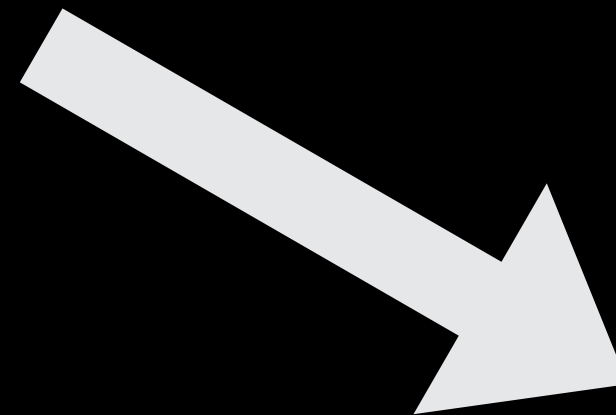
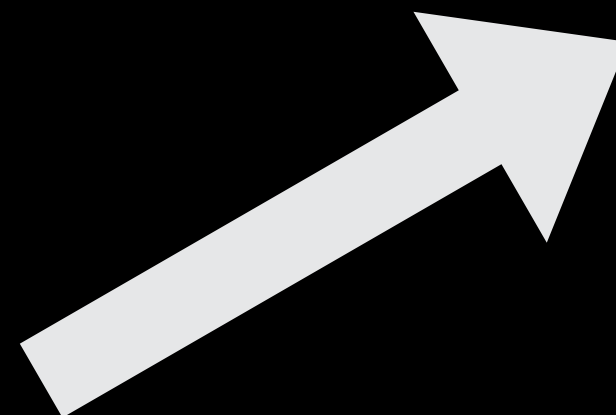
let to_list : int!eqn_assoc => int list = handler
| effect Choice _ k -> k true @ k false
| val x -> [x]
```

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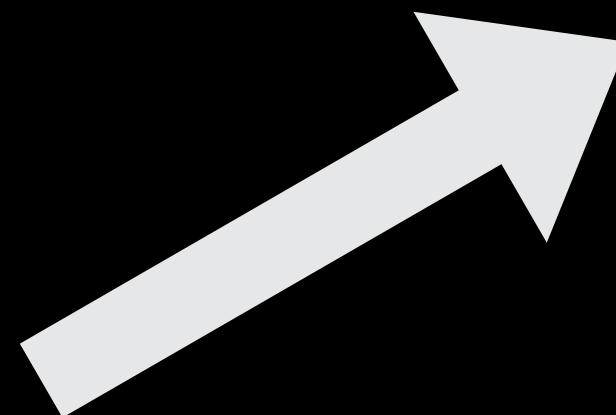


HANDLERS

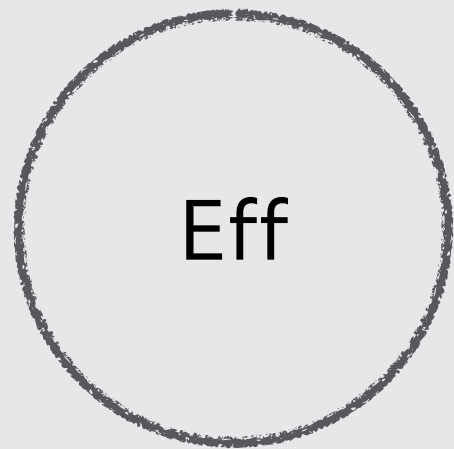




HANDLERS



The **simplest** way of efficiently executing Eff was **through OCaml**



efficient
execution



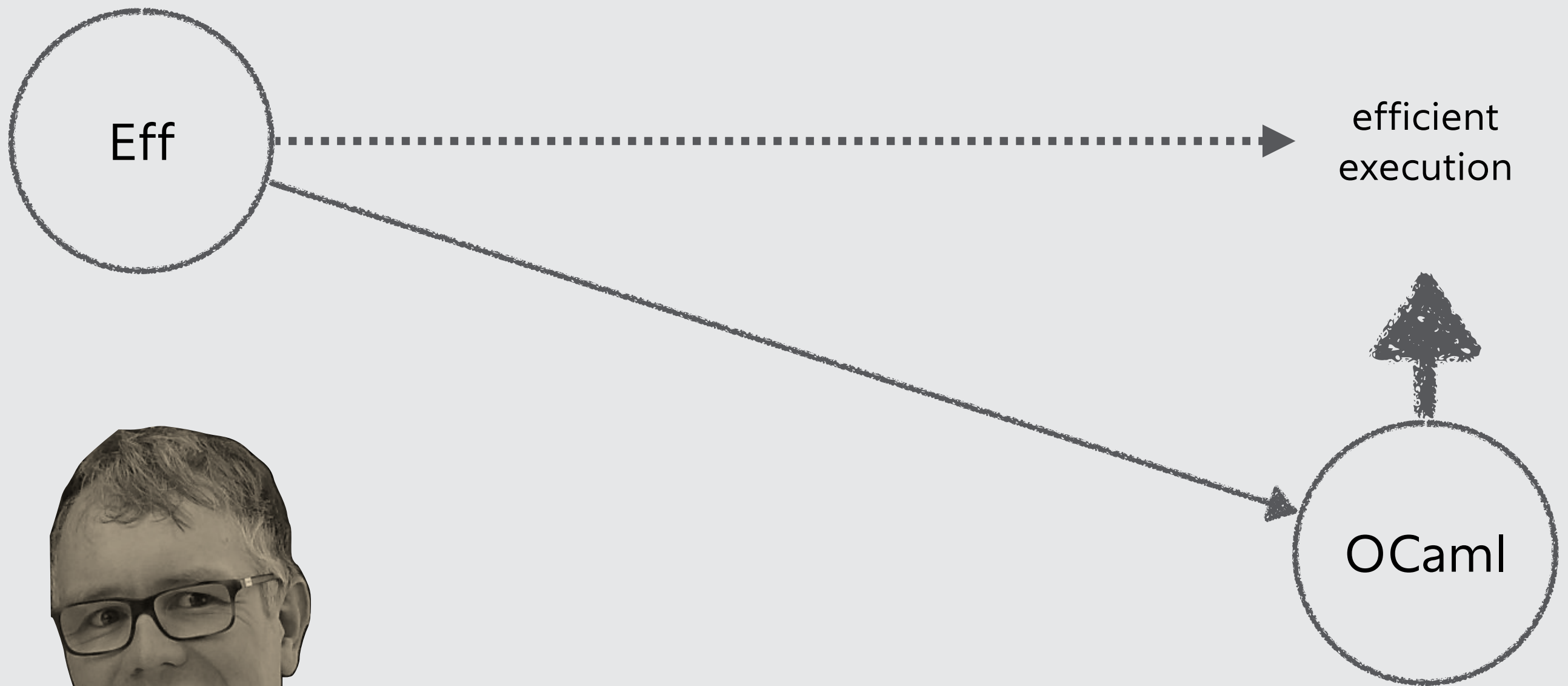
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Since OCaml did **not have handlers**, we did **monadic embedding**

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free monad

```
type 'a comp =  
  | Return of 'a  
  | Get of unit * (int -> 'a comp)  
  | Set of int * (unit -> 'a comp)  
  
type ('a, 'b) handler = { (* handler clauses *) }
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```

operations

```
val return : 'a -> 'a comp  
val (>>=) : 'a comp -> ('a -> 'b comp) -> 'b comp  
val map : ('a -> 'b) -> 'a comp -> 'b comp  
  
val get : unit -> int comp  
val set : int -> unit comp  
  
val handle : ('a, 'b) handler -> 'a comp -> 'b comp
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First component was a **purity-aware** translation

source Eff

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let y = perform Get in  
perform (Set (y + 1));  
loop (n - 1)
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purity-aware translation

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```

pu

$$\mathcal{C}(\sigma! \varphi) = \begin{cases} \mathcal{C}(\sigma) & \varphi = \emptyset \\ \mathcal{C}(\sigma) \text{ comp} & \varphi \neq \emptyset \end{cases}$$

```
get () >>= fun y ->
let i = (+) y in
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Second component was **inlining handler** definitions

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stateful function

```
let rec loop n =  
  if n = 0 then () else  
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let rec loop n =  
  if n = 0 then () else  
    let y = perform Get () in  
    perform (Set (y + 1));  
    loop (n - 1)
```

handler for state

```
let state_handler = handler  
| effect (Get ()) k -> (fun s -> k s s)  
| effect (Set s') k -> (fun _ -> k () s')  
| _ -> (fun s -> s)
```


Handlers get **pushed inside** other constructs

```
with state_handler handle
  if n = 0 then () else
    let y = perform Get () in
    perform (Set (y + 1));
    loop (n - 1)
```

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We **unfold the handler** once encountering a value or operation

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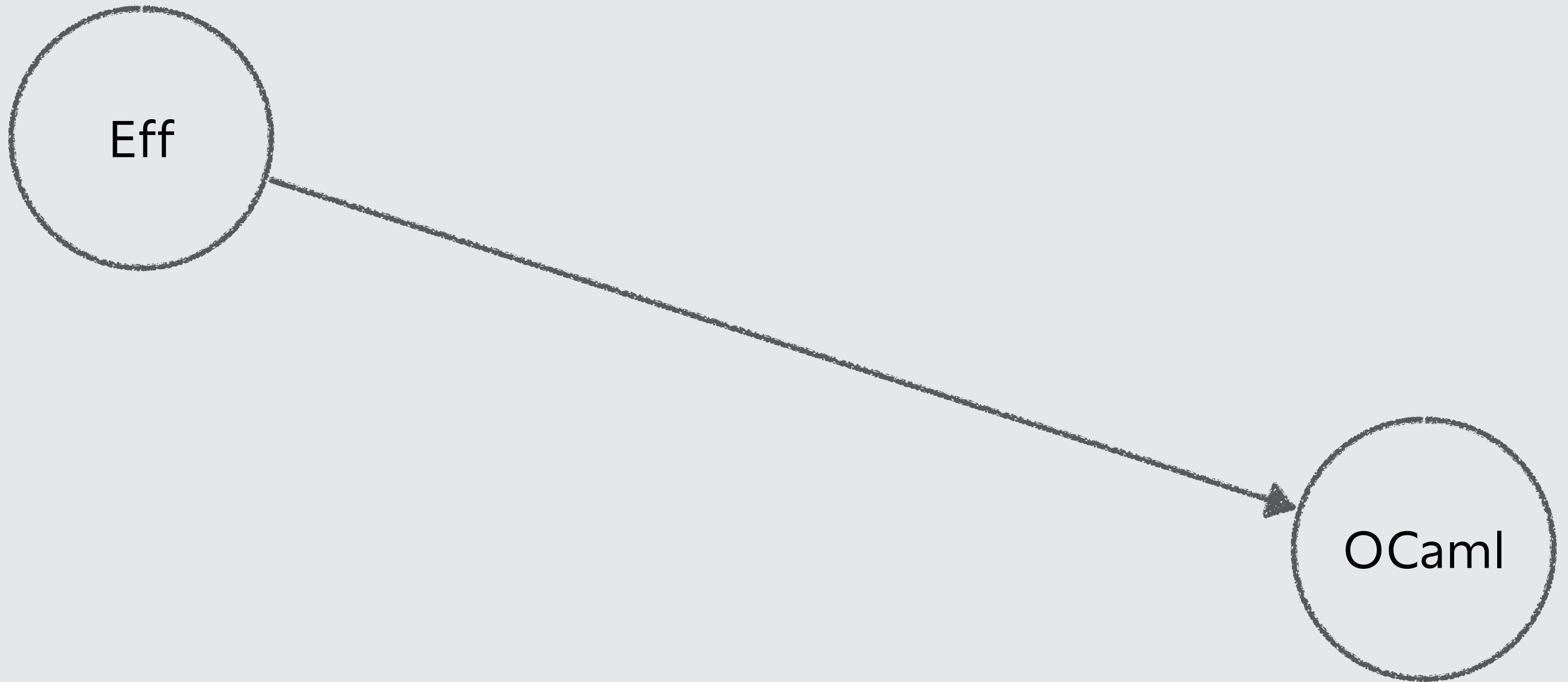
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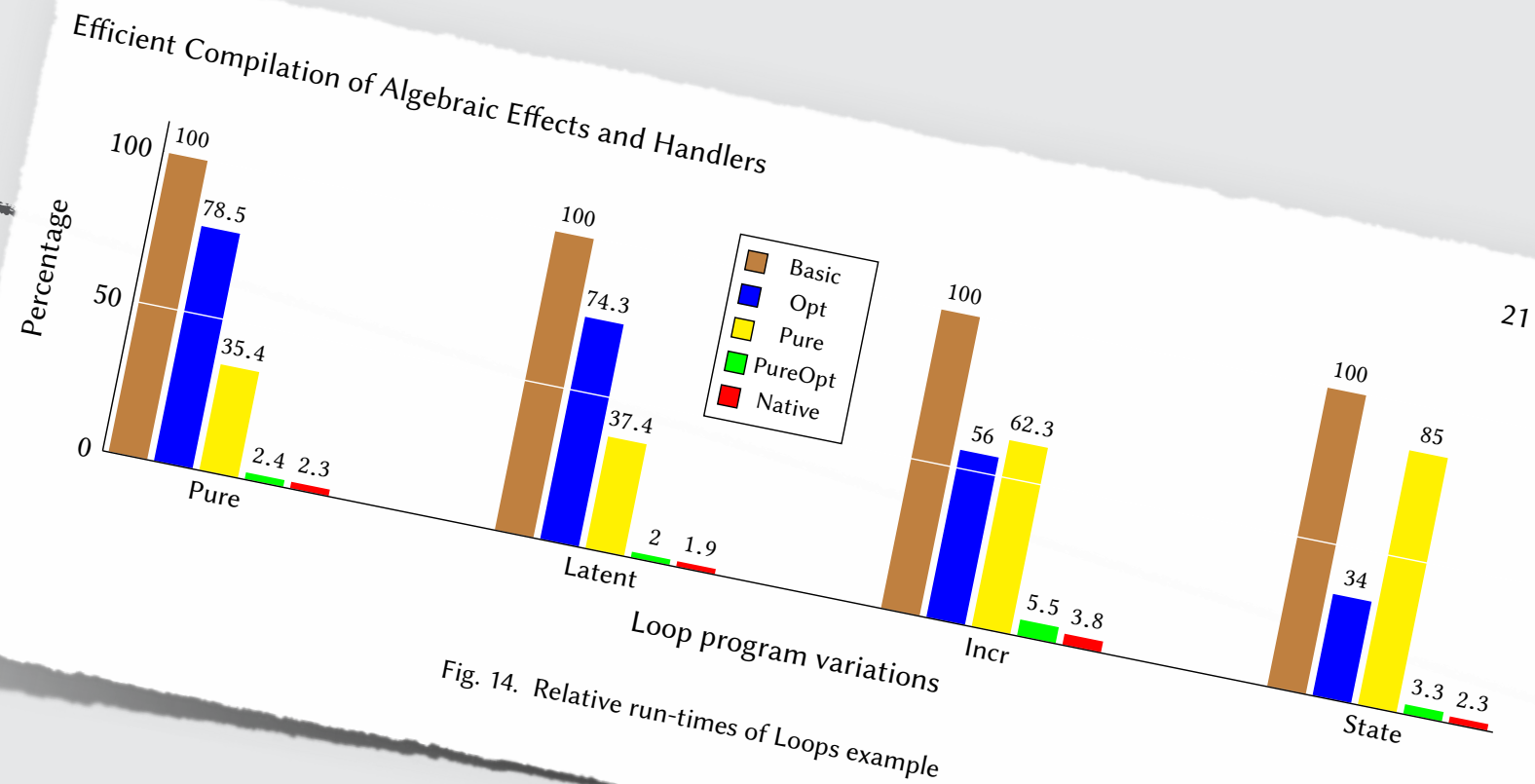
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let rec loop' n s =  
  if n = 0 then s else loop' (n - 1) (s + 1)
```

Purity-aware translation proved **tricky** due to **implicit typing** information



Purity-aware translation proved **tricky** due to **implicit typing** information

Eff

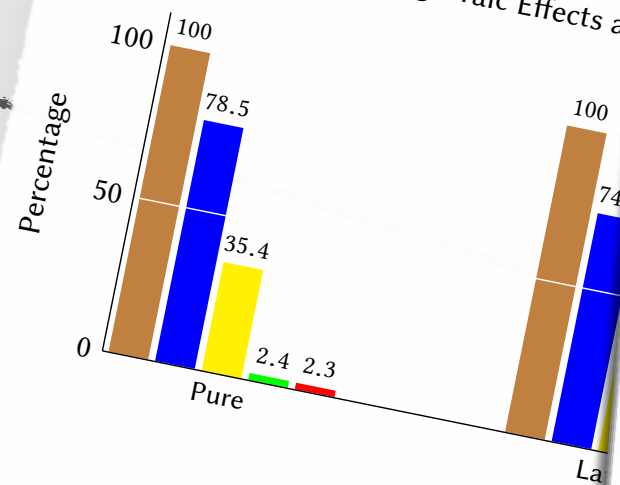


OCaml

Purity-aware translation proved **tricky** due to **implicit typing** information

Eff

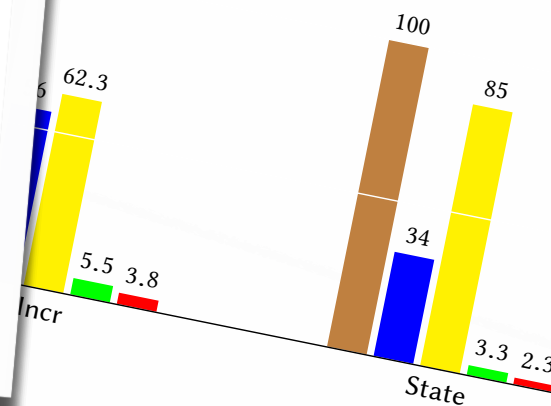
Efficient Compilation of Algebraic Effects and Handlers



Schrijvers
et al.

submitted
to ICFP
2017

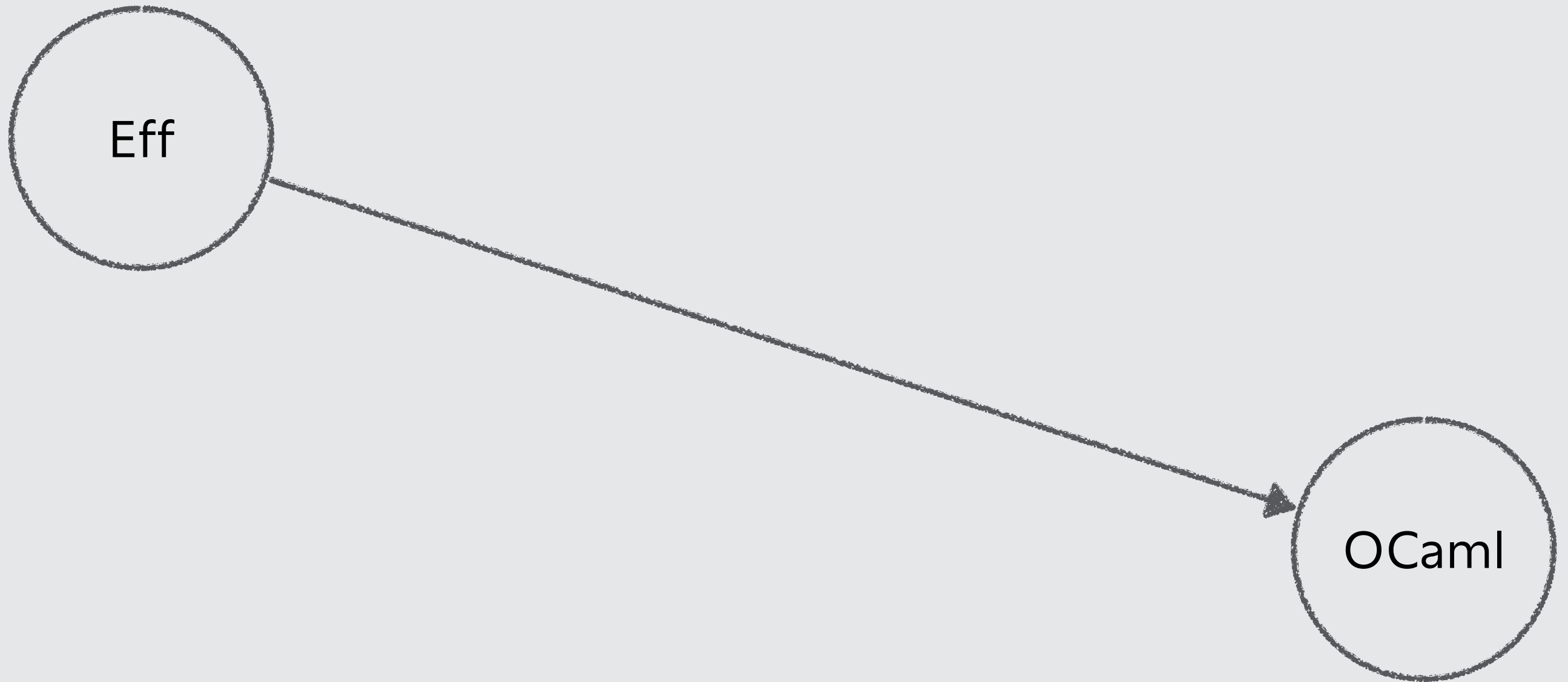
Fig. 14. Relative run-times of Loops example



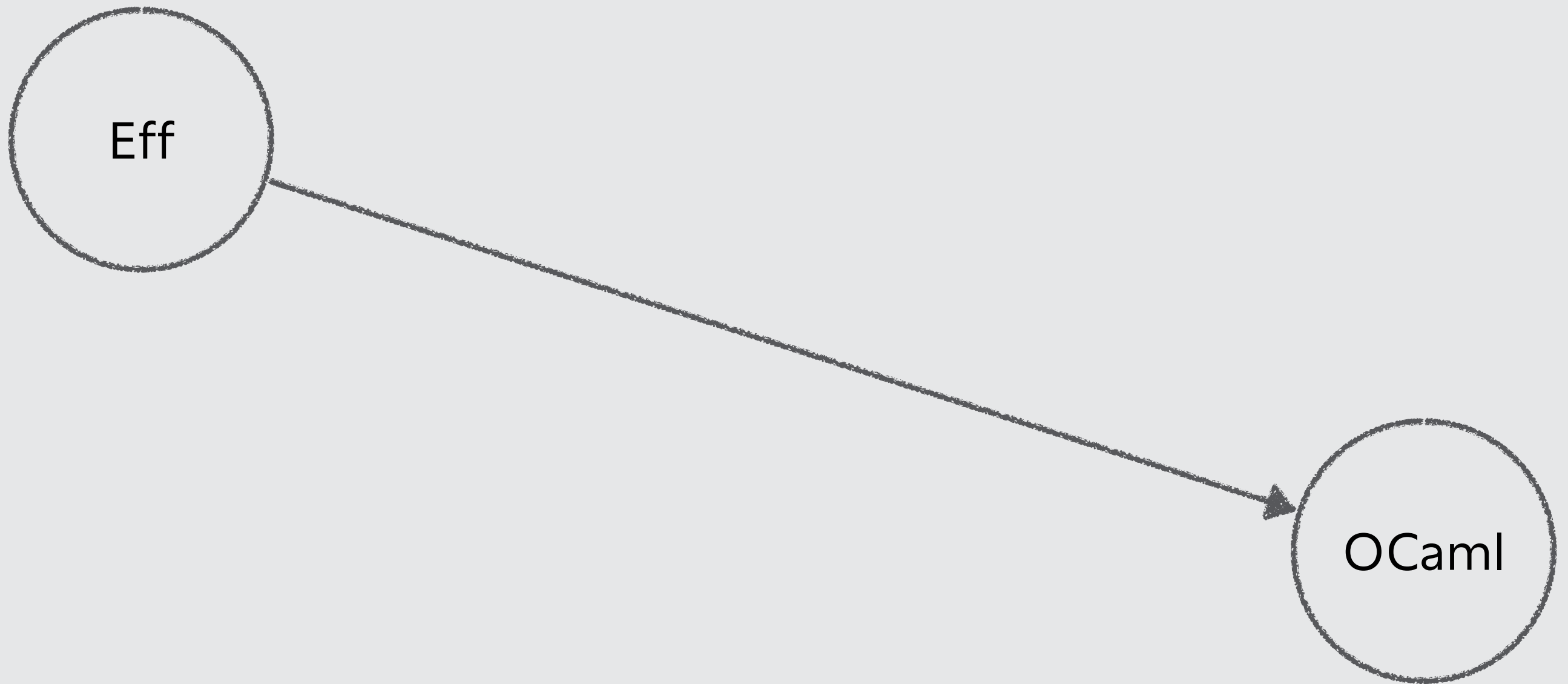
21

OCaml

Purity-aware translation proved **tricky** due to **implicit typing** information



One thing removed for simplicity were **effect instances**



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Eff

```
type 'a ref = effect  
  operation get: unit -> 'a  
  operation set: 'a -> unit  
end
```

```
let state r x = handler  
| r#get () k -> (fun s -> k s s)  
| r#set s' k -> (fun s -> k () s')  
| val y -> (fun s -> (y, s))  
| finally f -> f x
```

OCaml

One thing removed for simplicity were **effect instances**

Eff

```
type 'a ref = effect  
operation get: unit -> int  
operation set: int -> unit  
end  
let state r x = handler  
| #get () k -> (fun s -> k s s)  
| #set s' k -> (fun s -> k () s')  
| val y -> (fun s -> (y, s))  
| finally f -> f x  
finally f -> f x
```

OCaml

The main step was adding **coercions** as witnesses of **subtyping**

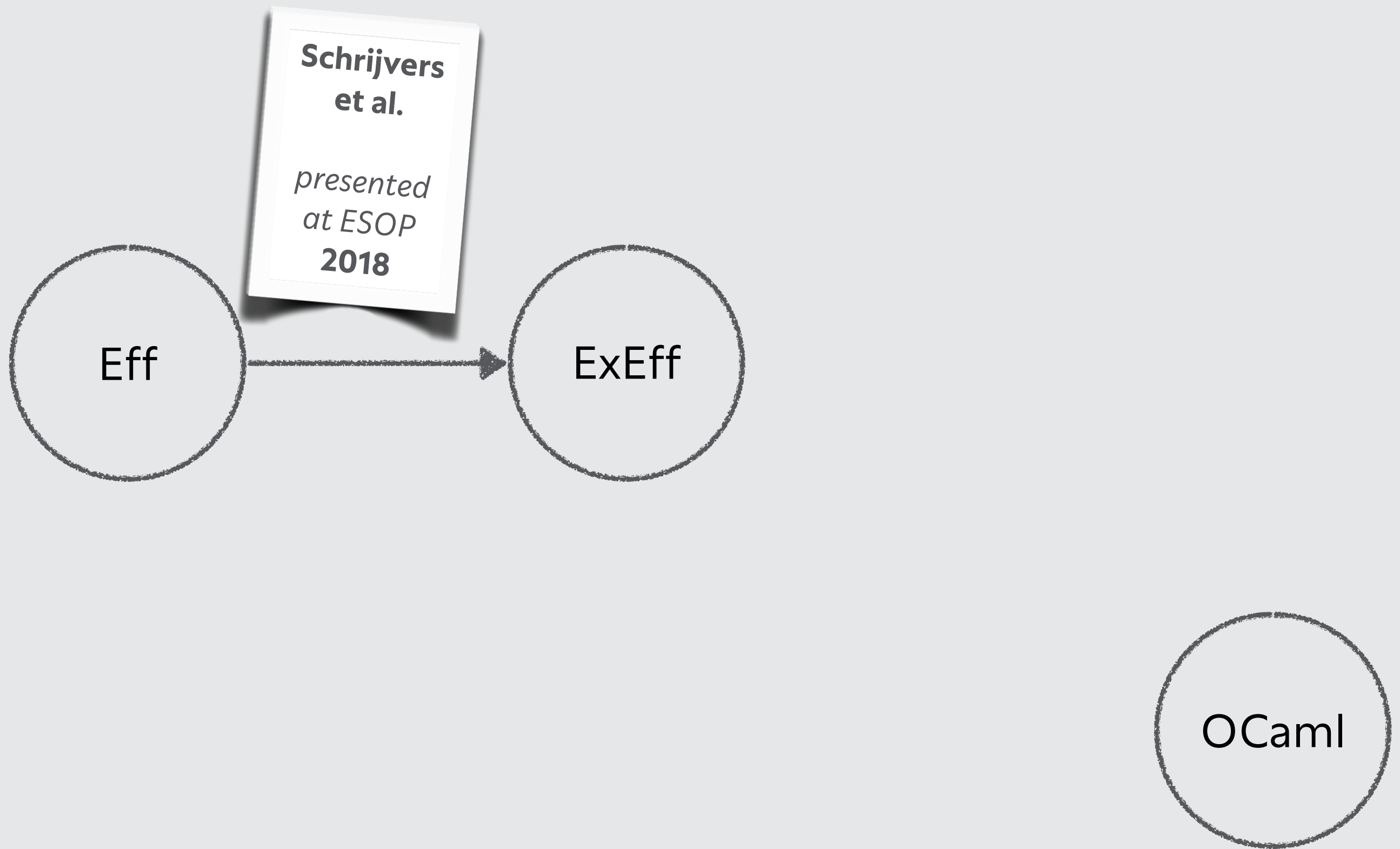


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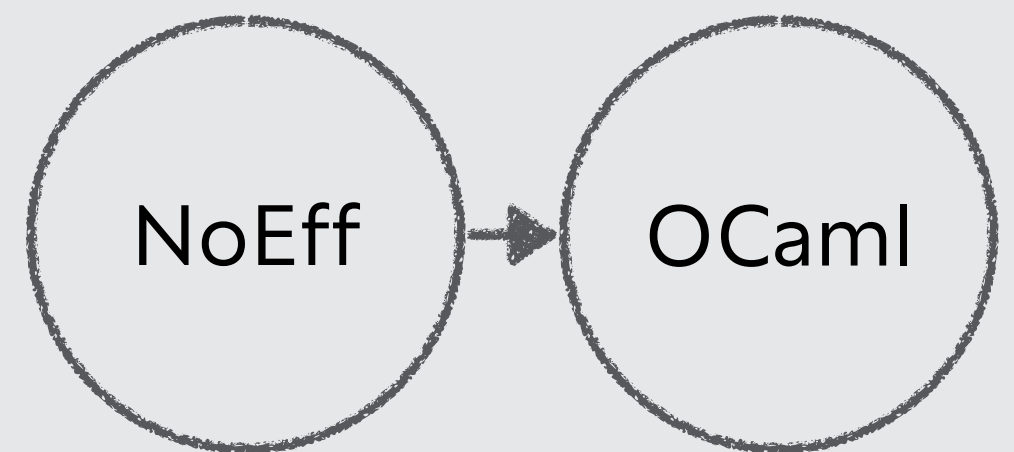
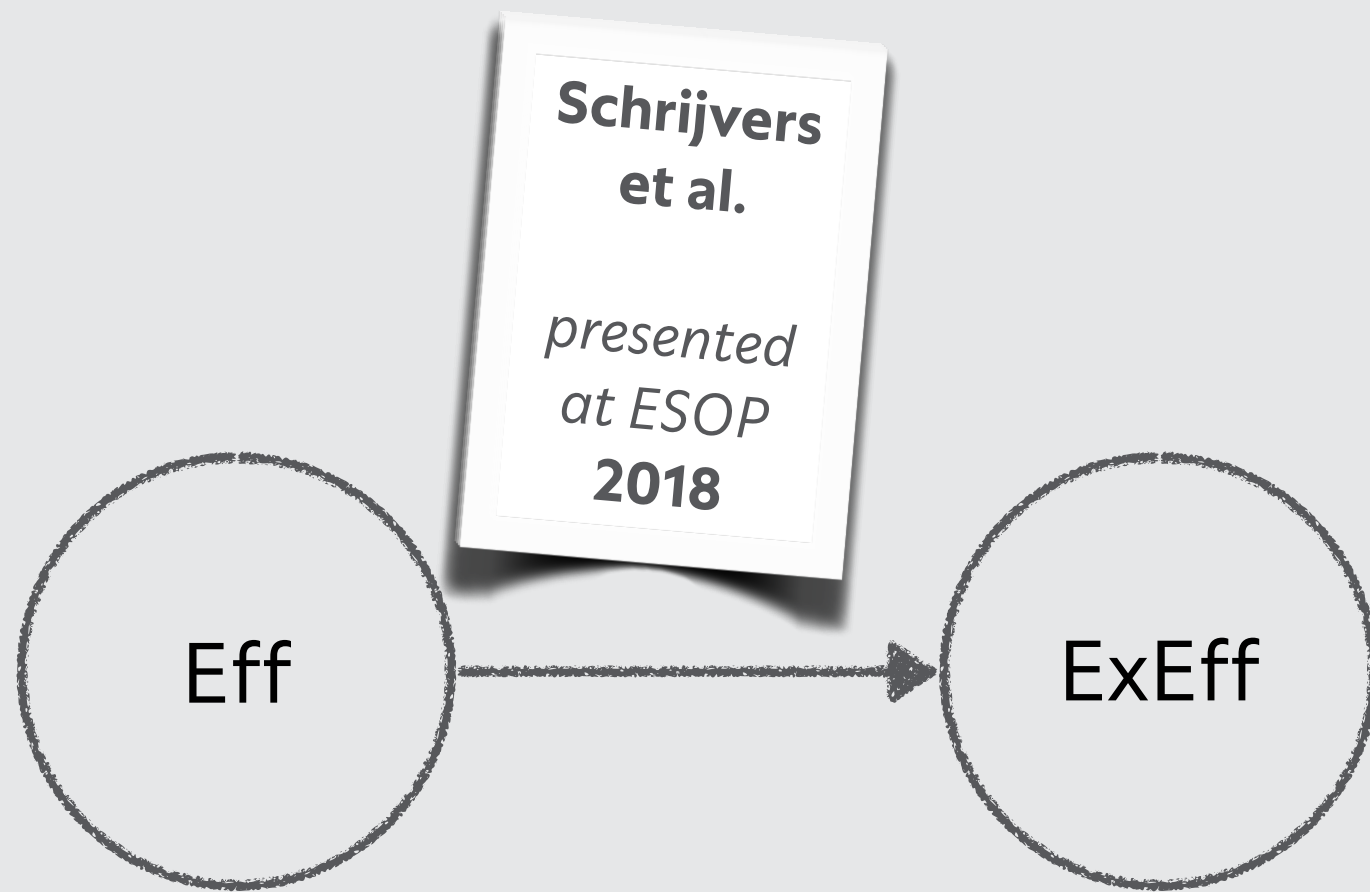


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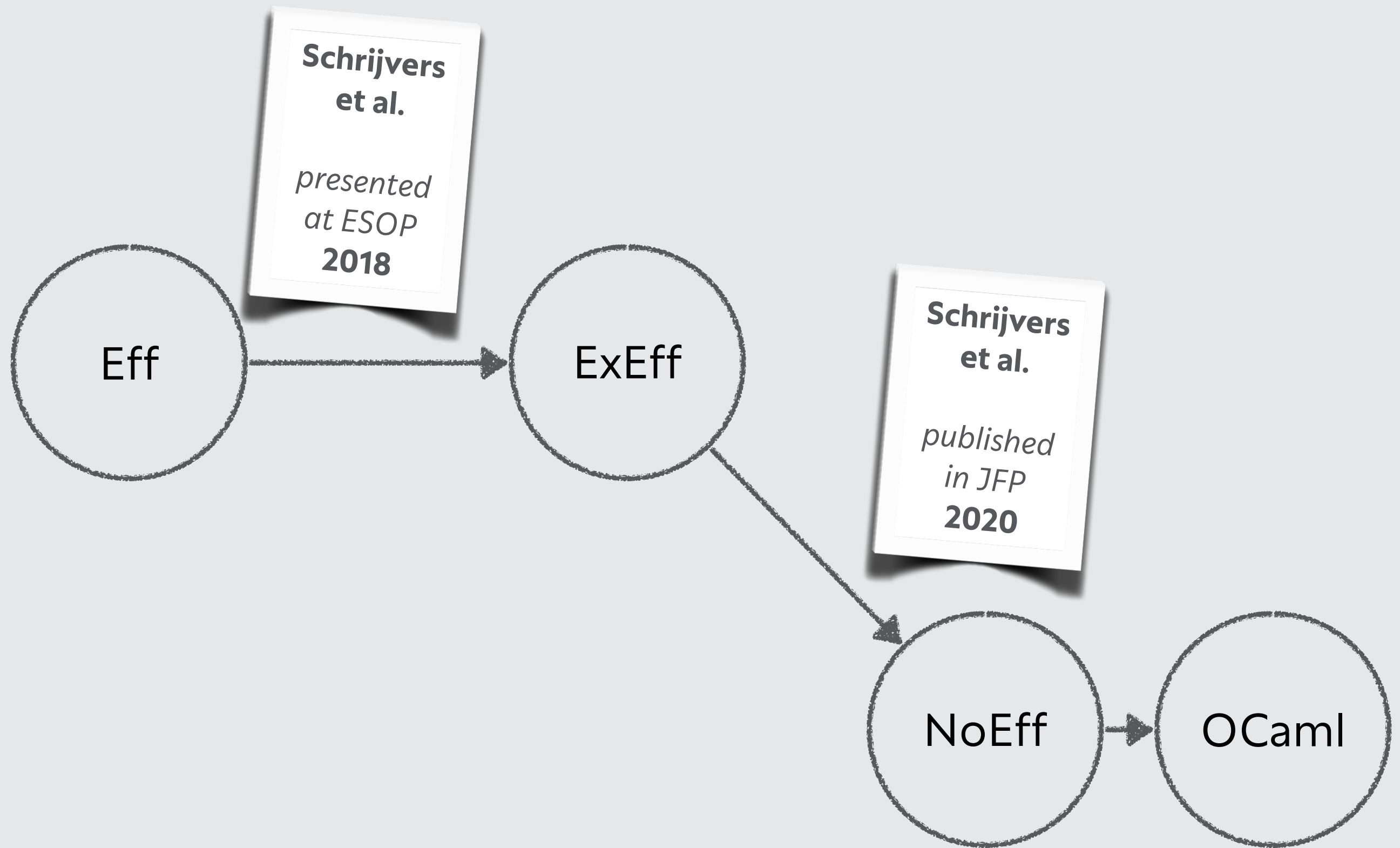
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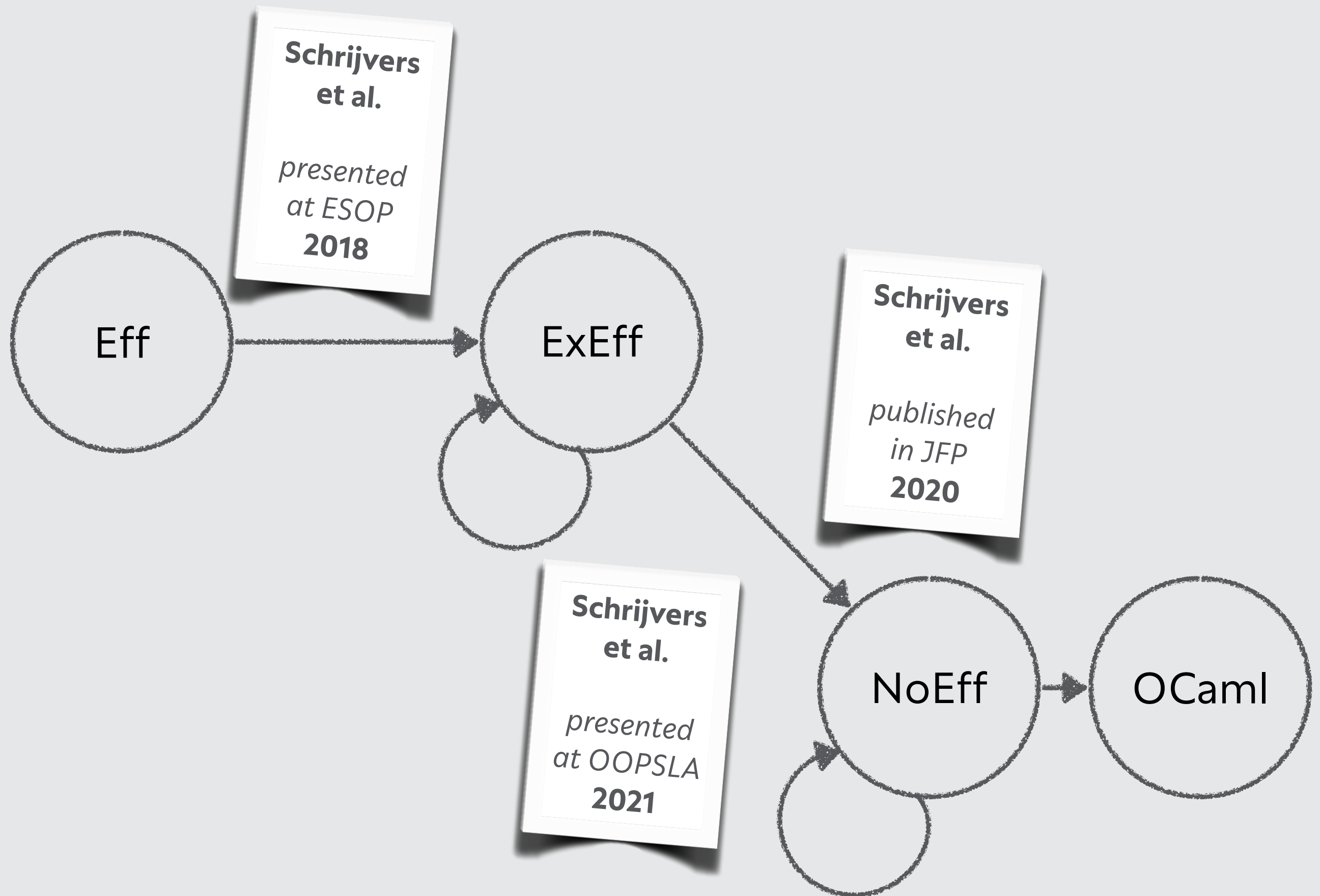
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The syntax of **types** and well-formedness rules for **coercions**

types

$$\sigma ::= b \mid \alpha \mid \sigma \rightarrow \underline{\tau} \qquad \underline{\tau} ::= \sigma ! \varphi$$

coercions

$$\frac{}{\Xi \vdash \langle \sigma \rangle : (\sigma <: \sigma)} \qquad \frac{\omega : (\sigma <: \sigma') \in \Xi}{\Xi \vdash \omega : (\sigma <: \sigma')}$$
$$\frac{\Xi \vdash \omega_v : (\sigma' <: \sigma) \qquad \Xi \vdash \omega_c : (\underline{\tau} <: \underline{\tau}')}{\Xi \vdash \omega_v \rightarrow \omega_c : ((\sigma \rightarrow \underline{\tau}) <: (\sigma \rightarrow \underline{\tau}'))}$$

$$\frac{\Xi \vdash \omega_v : (\sigma <: \sigma') \qquad \Xi \vdash \varpi : (\varphi <: \varphi')}{\Xi \vdash \omega_v ! \varpi : (\sigma ! \varphi <: \sigma' ! \varphi')}$$

When compiling to **OCaml**, coercions are mapped into **functions**

$$\mathcal{C}(\langle \sigma \rangle) = \text{id}$$

$$\mathcal{C}(\omega_i) = w_i$$

$$\mathcal{C}(\omega_v \rightarrow \omega_c) = \text{fun } f \mapsto x \mapsto (f(x \triangleright \mathcal{C}(\omega_v)) \triangleright \mathcal{C}(\omega_c))$$

$$\mathcal{C}(\omega_v ! \varpi) = \begin{cases} \mathcal{C}(\omega_v) & \varpi : \emptyset \subseteq \emptyset \\ \text{return} \circ \mathcal{C}(\omega_v) & \varpi : \emptyset \subseteq \varphi \\ \text{map } \mathcal{C}(\omega_v) & \varpi : \varphi \subseteq \varphi' \end{cases}$$

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Translating a **polymorphic** function incurs **additional parameters**

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Eff source

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let apply_zero f = f 0 in  
apply_zero cos
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OCaml translation

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Coercions can be **replaced without impacting** the semantics

OPTIMISING SUBTYPING COERCIONS IN
A POLYMORPHIC CALCULUS WITH EFFECTS

FILIP KOPRIVEC ^{a,b} AND MATIJA PRETNAR ^{a,b}

^a University of Ljubljana, Faculty of Mathematics and Physics, Jadranska 19, SI-1000 Ljubljana, Slovenia

^b Institute of Mathematics, Physics and Mechanics, Jadranska 19, SI-1000 Ljubljana, Slovenia
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e-mail address: matija.pretnar@fmf.uni-lj.si

ABSTRACT. Algebraic effects and handlers are becoming increasingly popular as a way to structure and reason about effectful computations. However, the performance of effectful programs is often a concern, with multiple different optimization techniques being proposed. This paper focuses on existing compilation scheme using type-and-effect directed optimizations, by providing optimizations for polymorphic version of type-and-effect based intermediate language by decreasing the amount of explicit coercions in the final program. We present a simple polymorphic type system and calculus with support for effects together with requirements for the language and the type system needed by the optimizations to be correct with respect to subtyping. We identify a set of independent simplification primitives, that are safe from type perspective and can be used to simplify the program. Denotational semantics for the language is provided, together with the requirements for the optimization phases to be correct with the respect to the semantics and proof that previously mentioned simplification primitives are correct with respect to the semantics. Finally, we provide an implementation of the constraint simplification algorithm in Eff language and evaluate the performance of the optimizations on the standard library, that contains a large number of polymorphic functions and is a good representative of the real-world code. The results show that the optimizations are able to greatly decrease the amount of explicit coercions and monadic artifacts in the final program.

Write abstract.

INTRODUCTION

Recent years have seen an increase in the number of programming languages that support algebraic effect handlers [PP03, PP13]. With a widespread usage, the need for performance is becoming ever more important. And there are two main ways for achieving it: an efficient runtime [DWS⁺15, SDW⁺21], or an optimising compiler [SBO20, XL21, KKPS21], which we focus on in this paper.

Key words and phrases: Computational effects, Optimizing compilation, Polymorphic compilation, Denotational semantics.
This material is based upon work supported by the Air Force Office of Scientific Research under awards number FA9550-17-1-0326 and FA9550-21-1-0024.

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ABSTRACT. Algebraic effects and handlers structure and reason about

Corollary 5.4. *Let $\Xi; \cdot \vdash v : A$ be a well-typed closed value, Φ a complete phase such that $\Phi(\Xi, \text{fp}(A)) = (\Xi', \sigma)$. Then, for any instantiation $\vdash_{\text{subst}} \eta : \Xi$, there exists an instantiation $\vdash_{\text{subst}} \eta' : \Xi'$ and a coercion $\vdash \gamma_v : \eta'(\sigma(A)) \leq \eta(A)$ such that*

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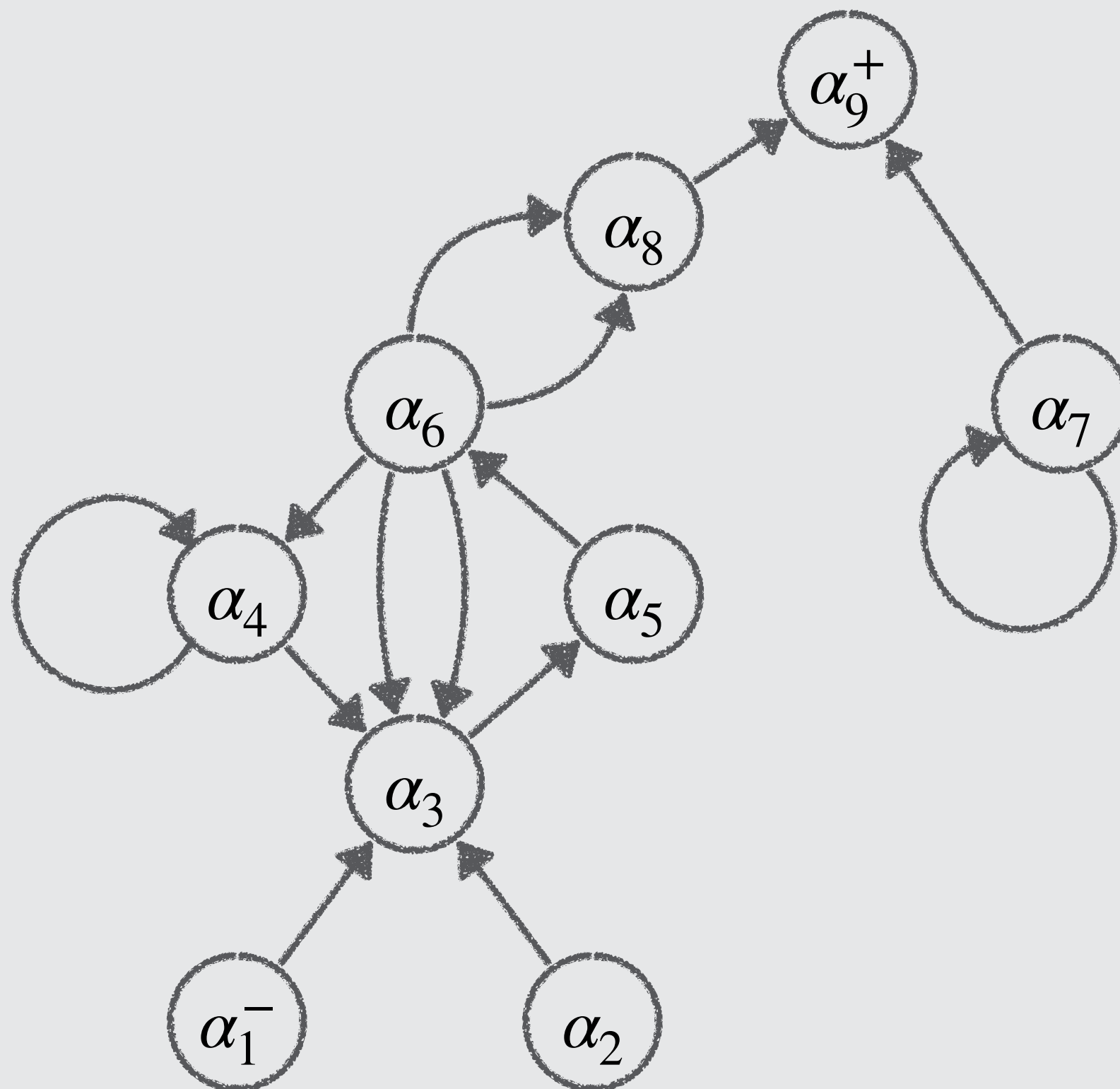
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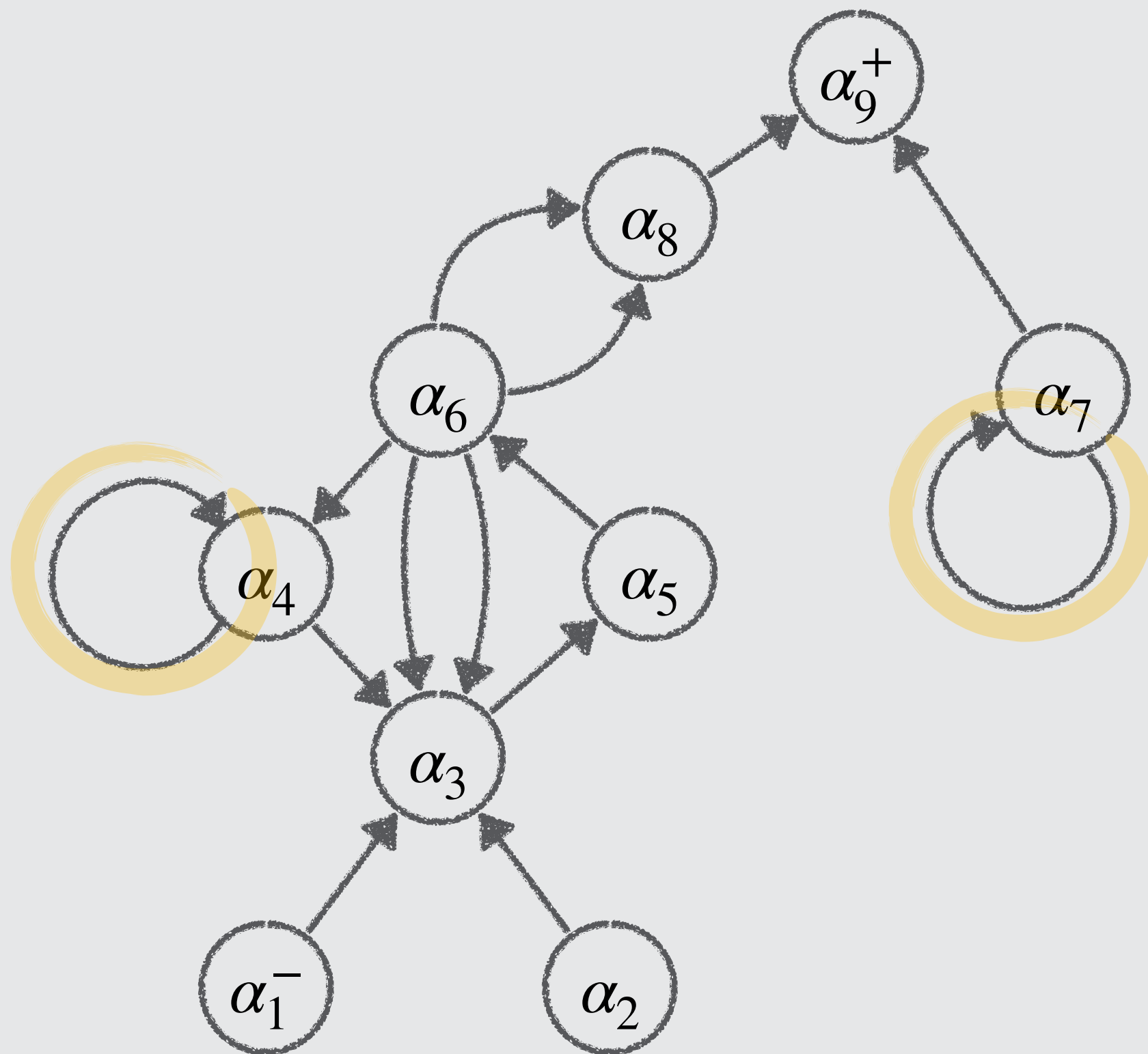
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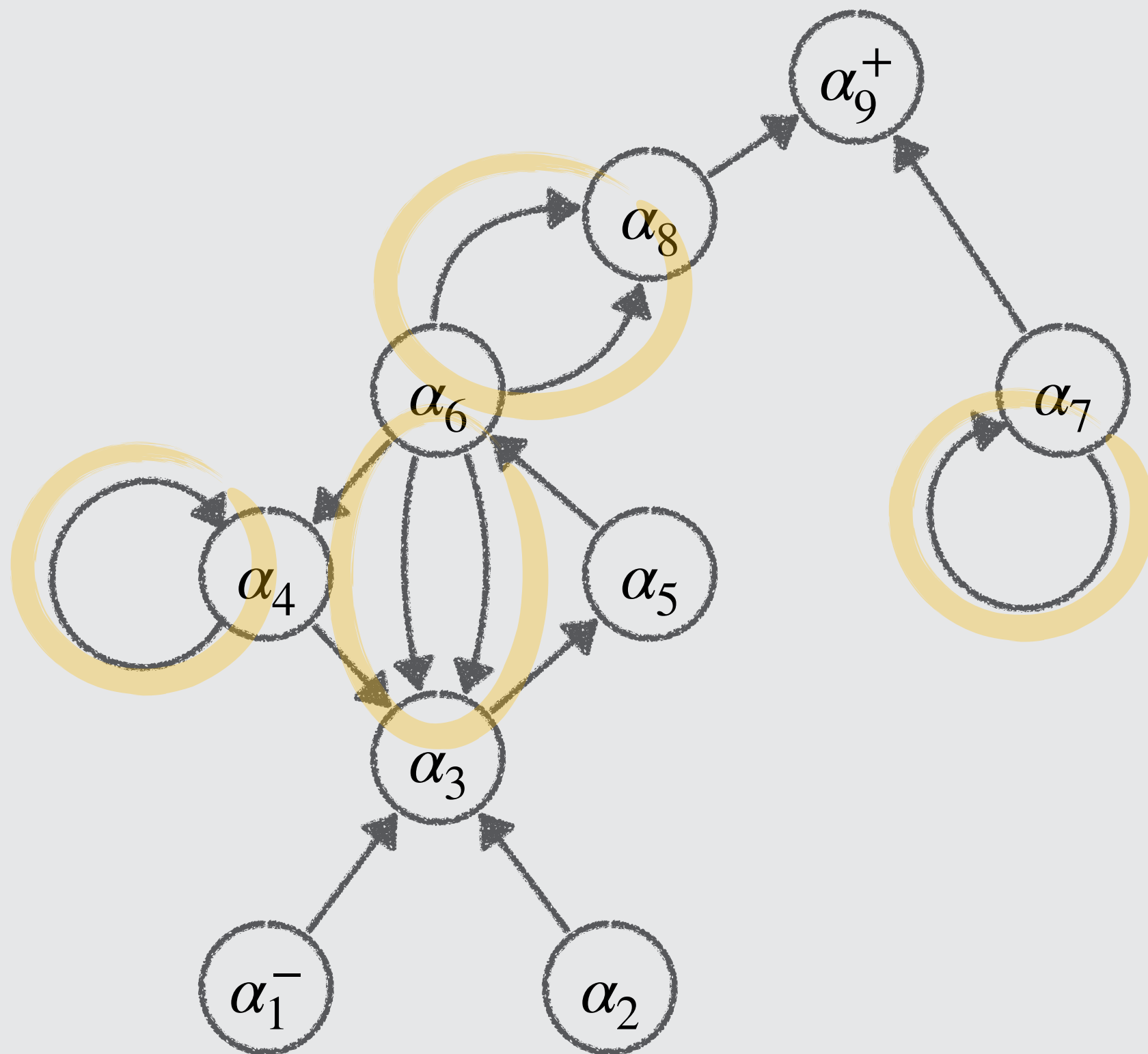
Constraints can be represented with **directed graphs**



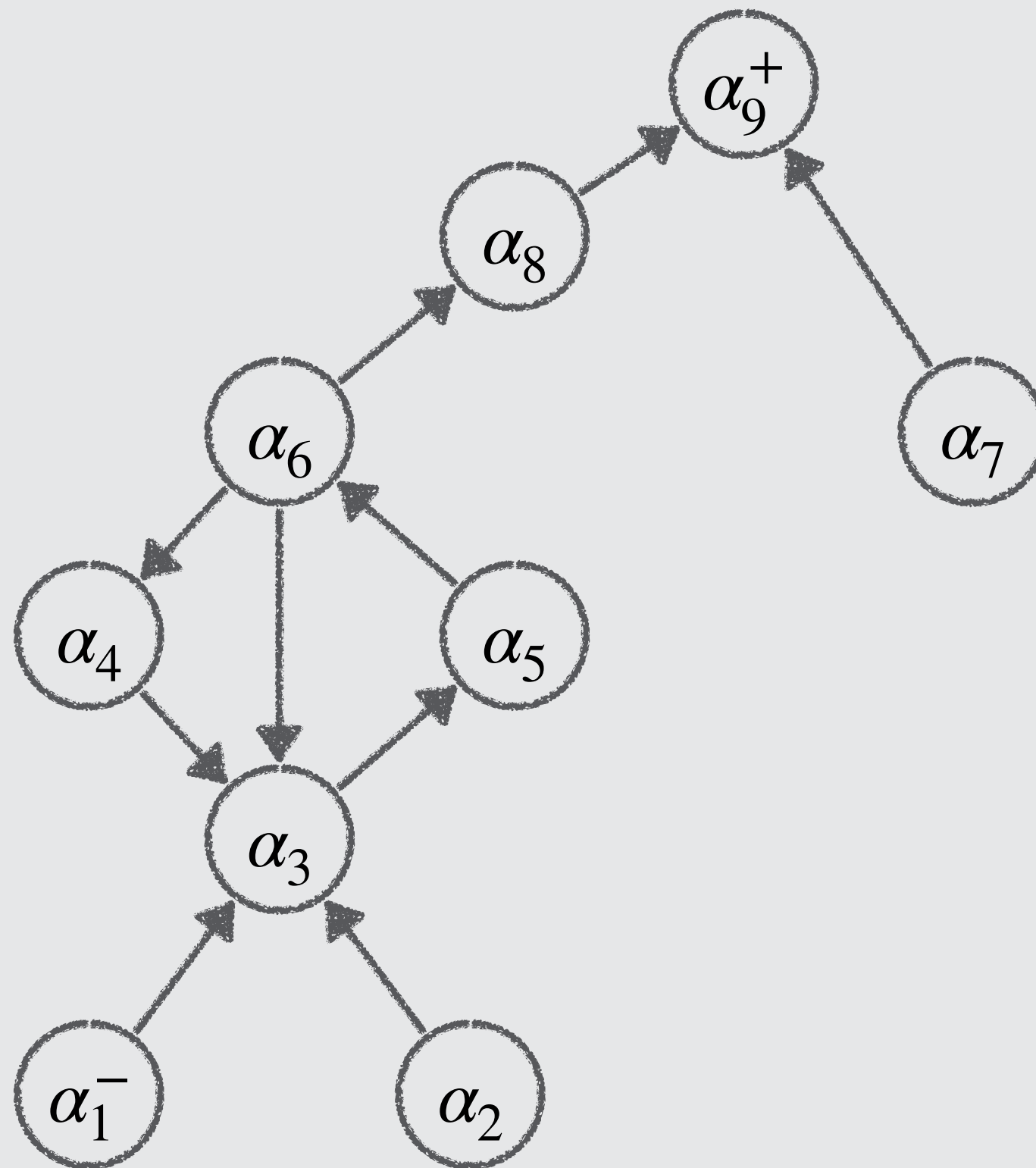
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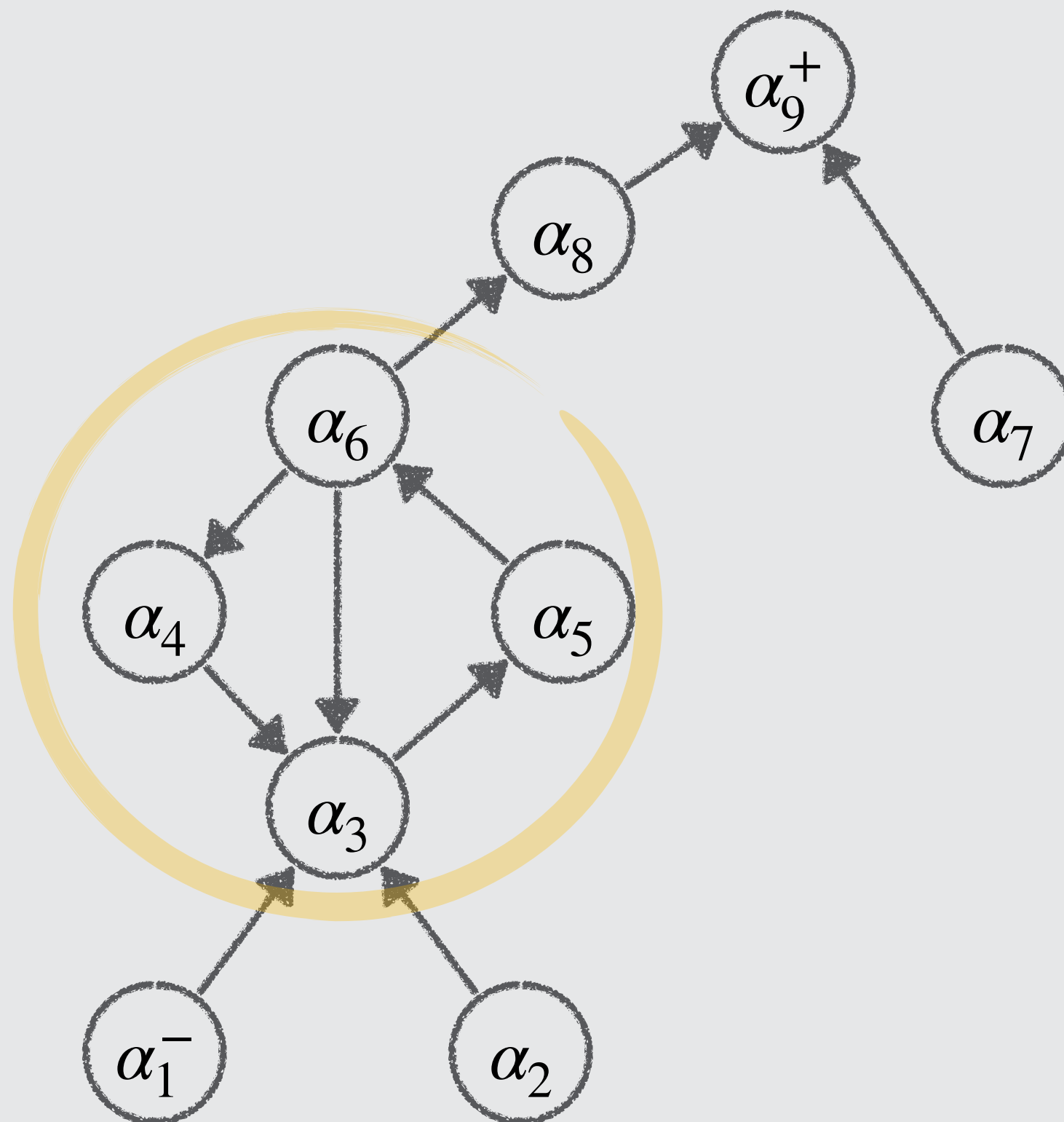
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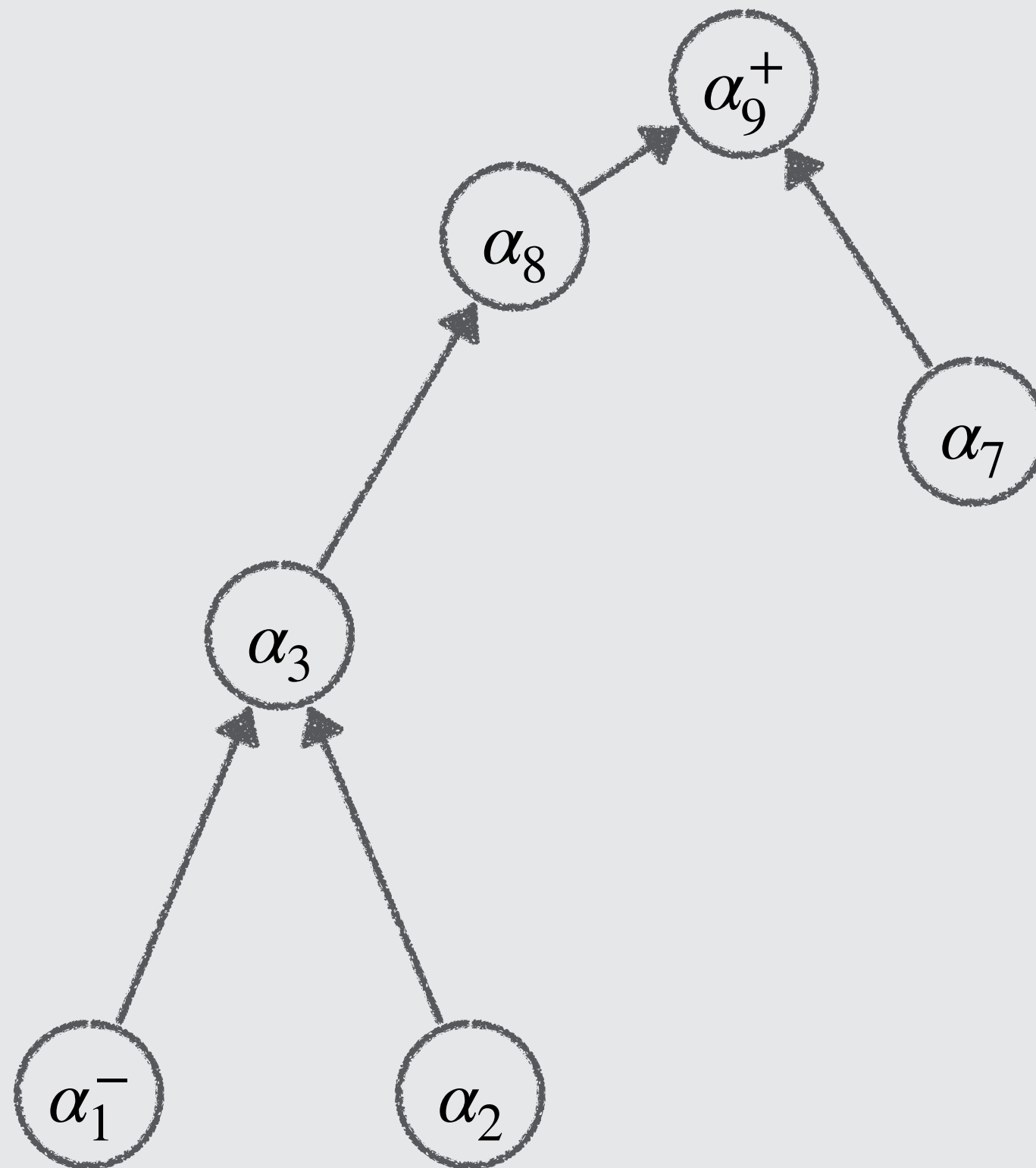
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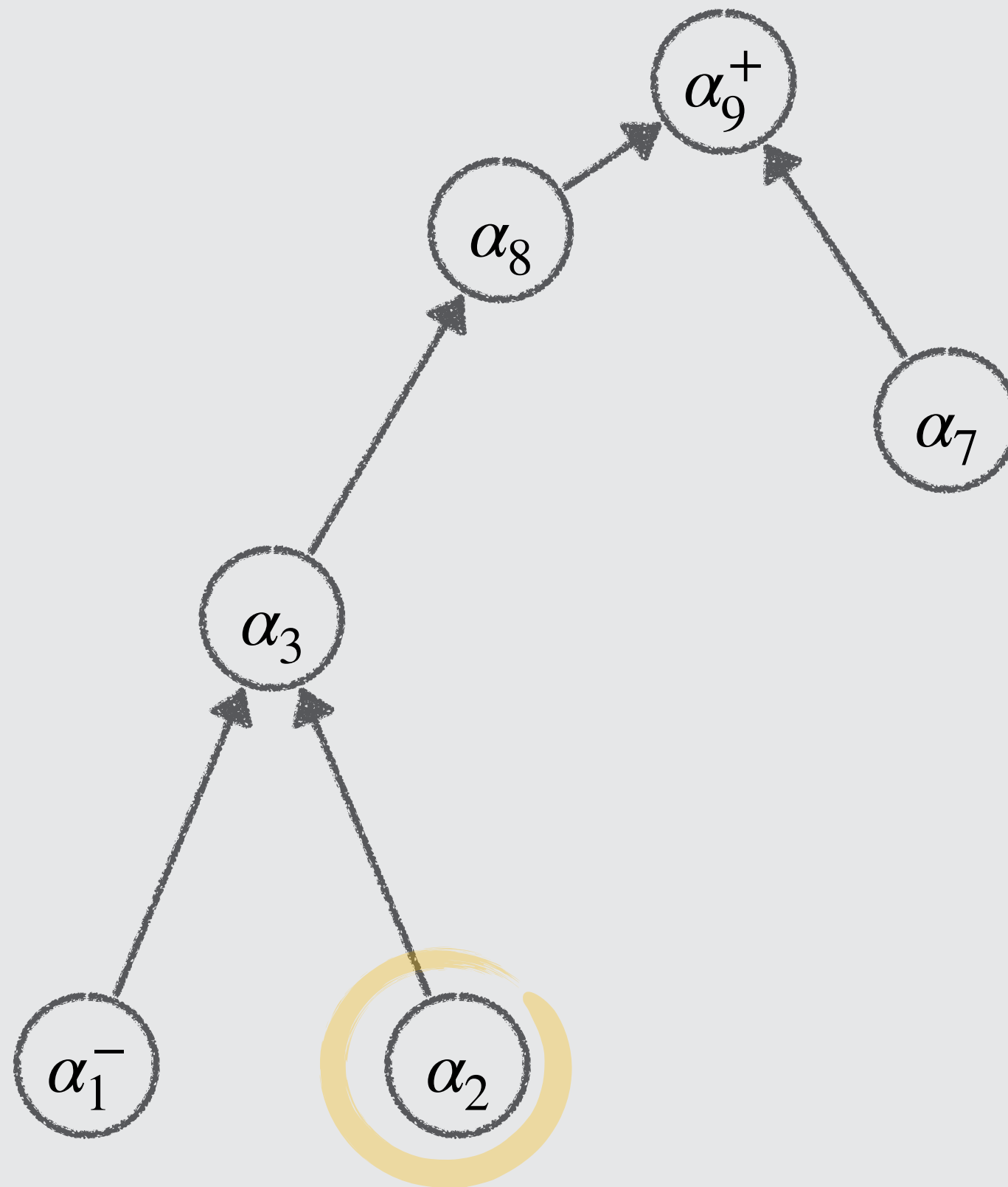
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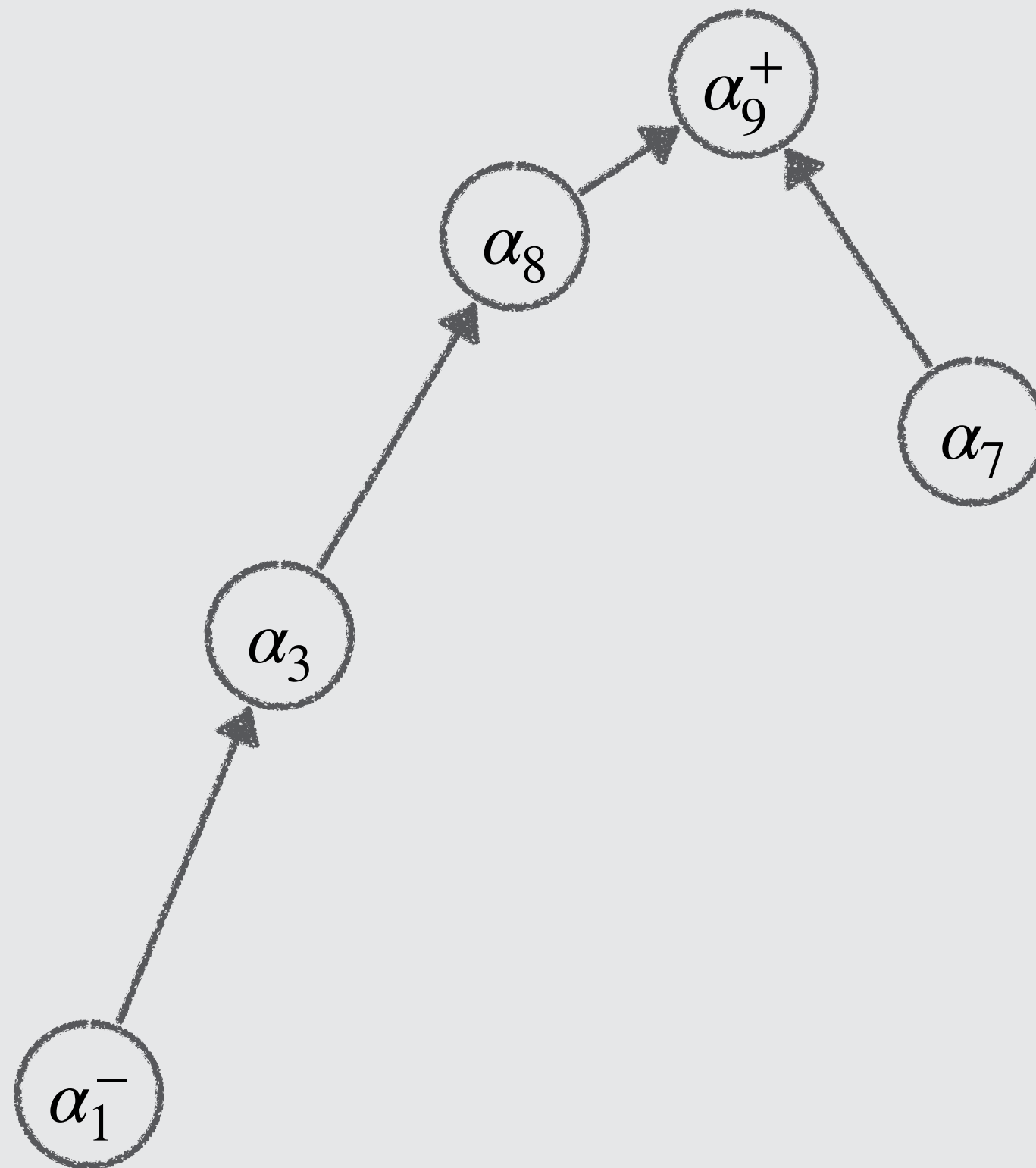
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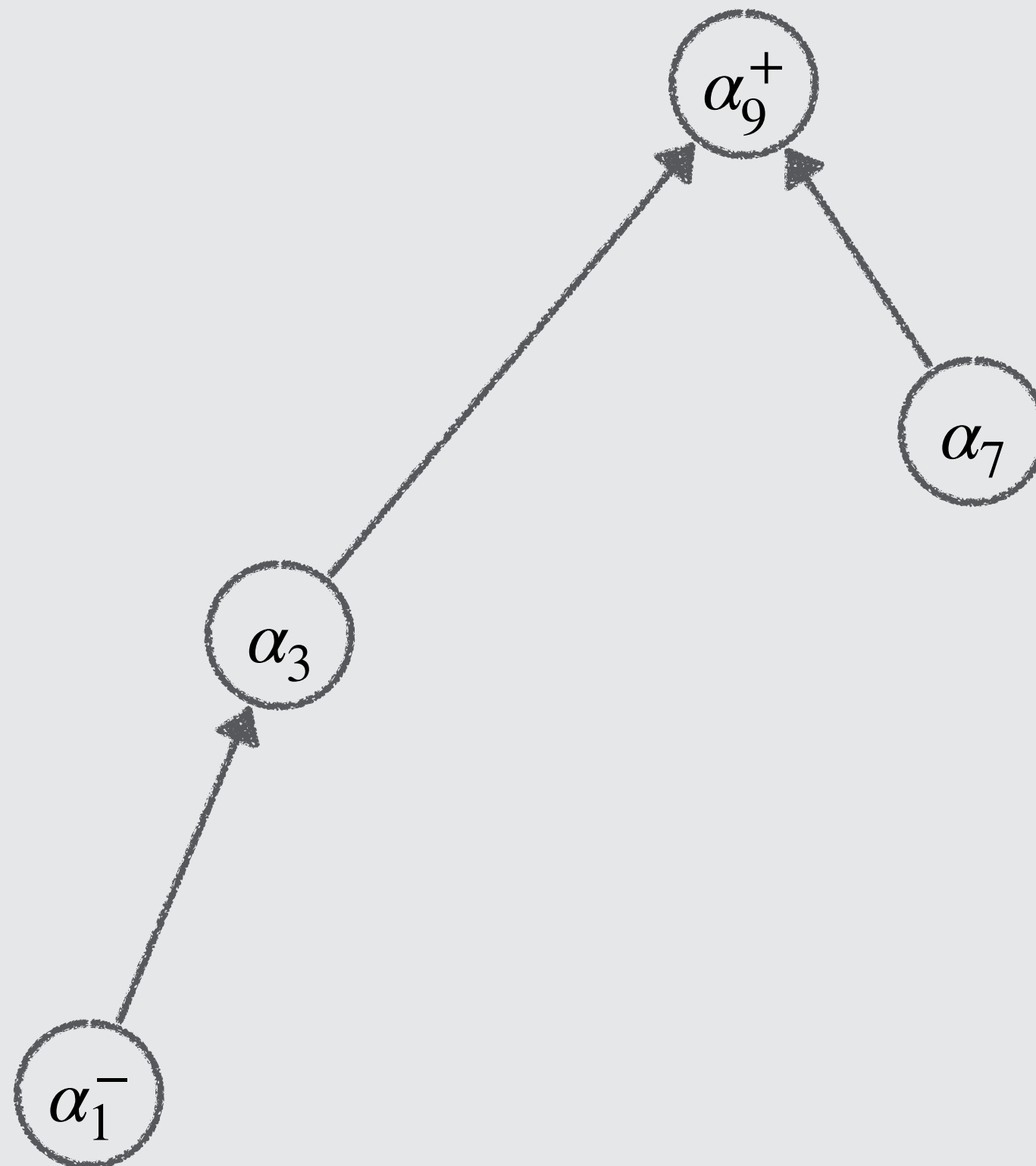
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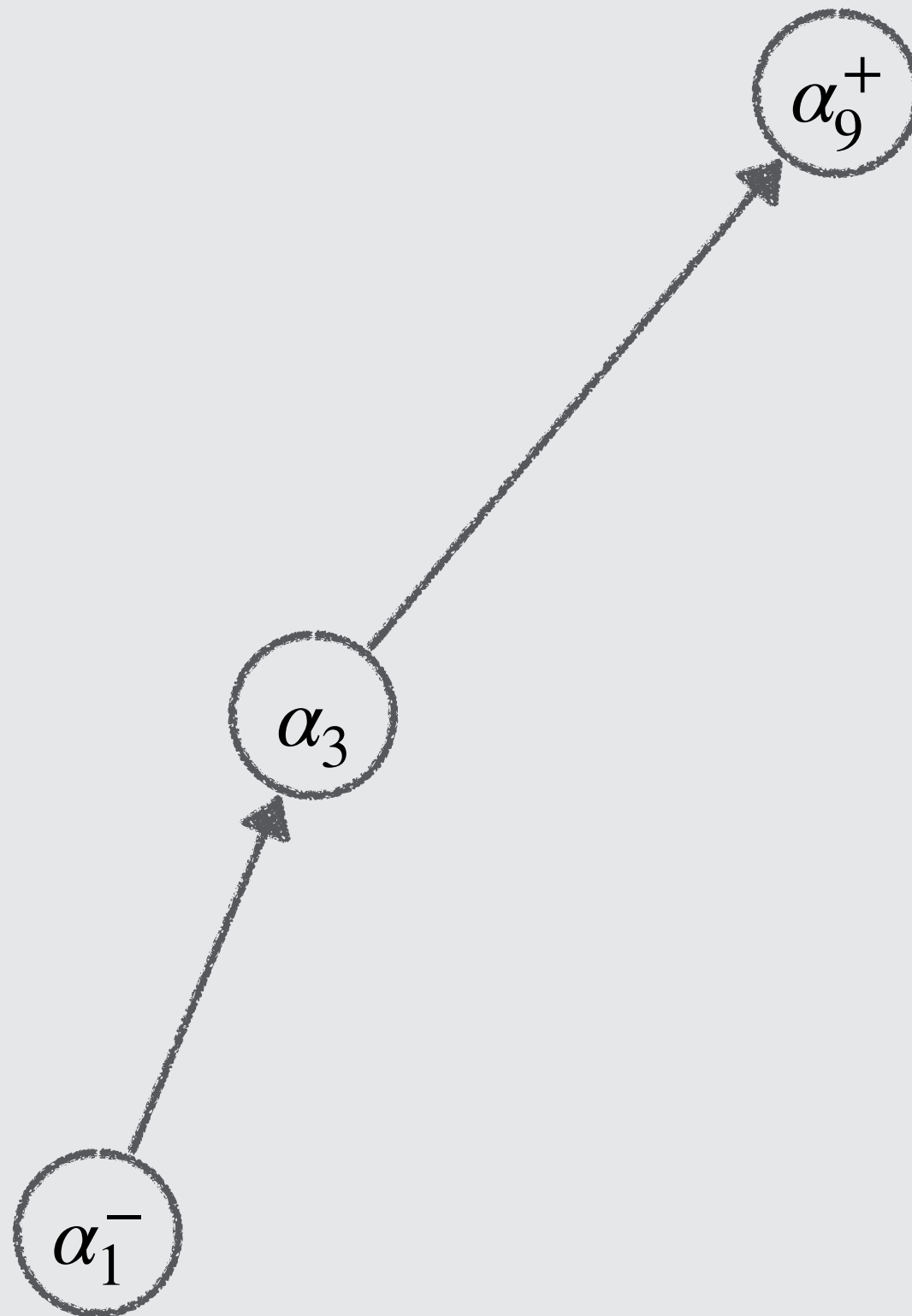
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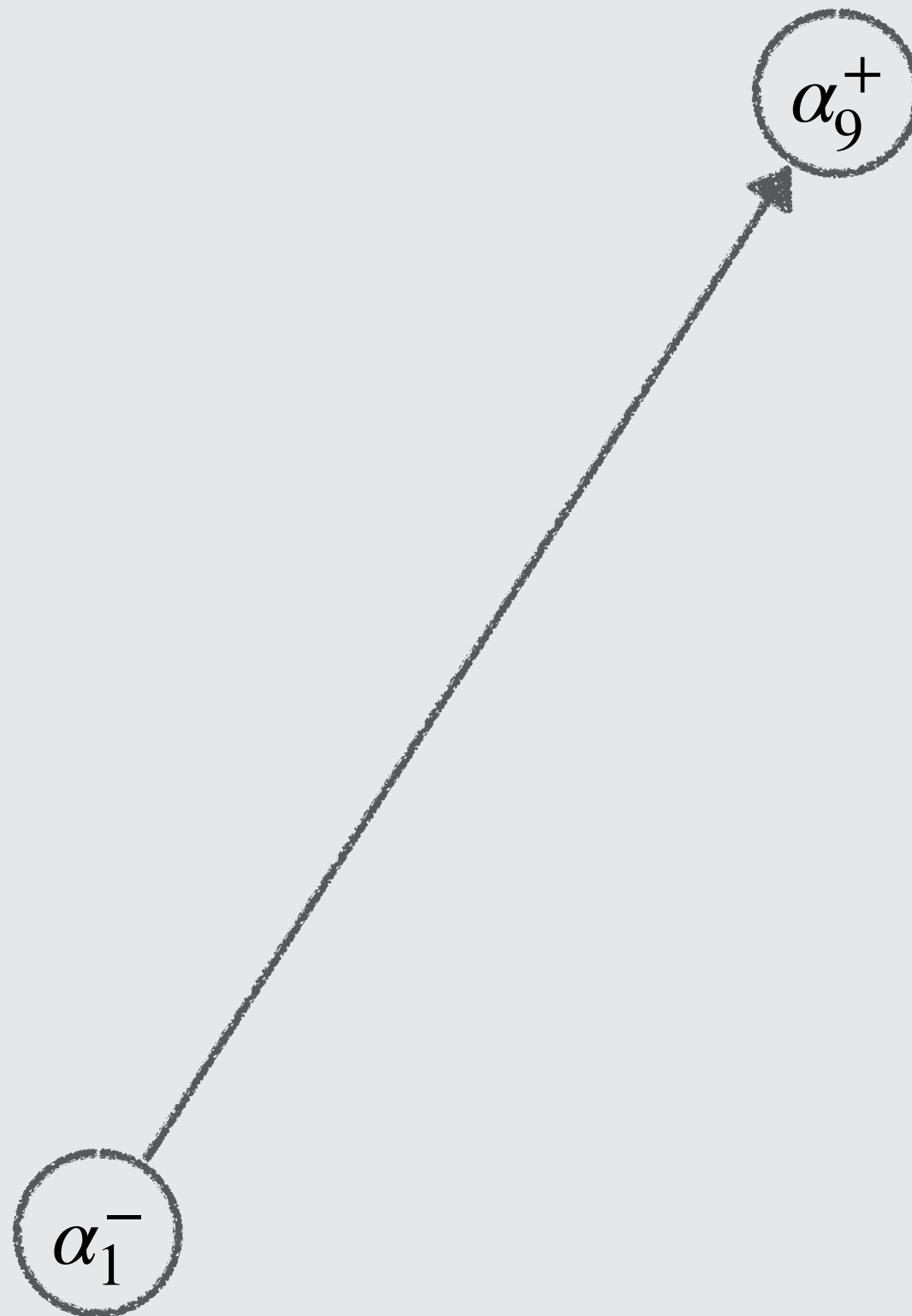
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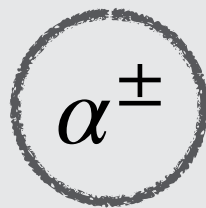
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Even though not **canonical**, we significantly simplify compiled **Eff stdlib**

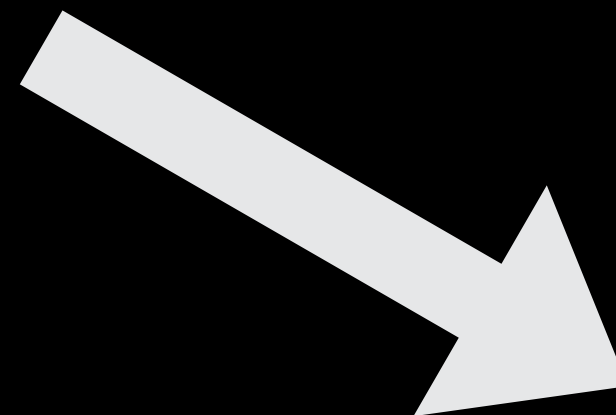
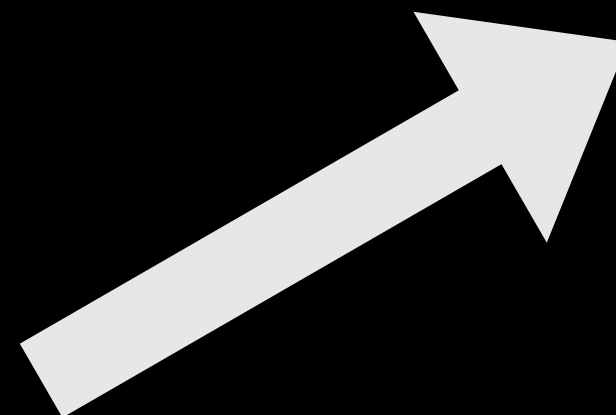
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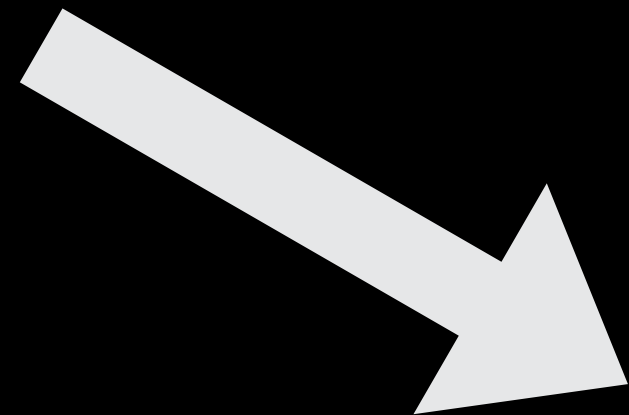
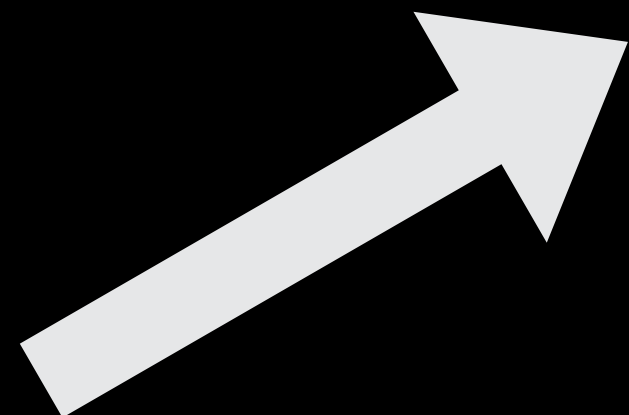


HANDLERS





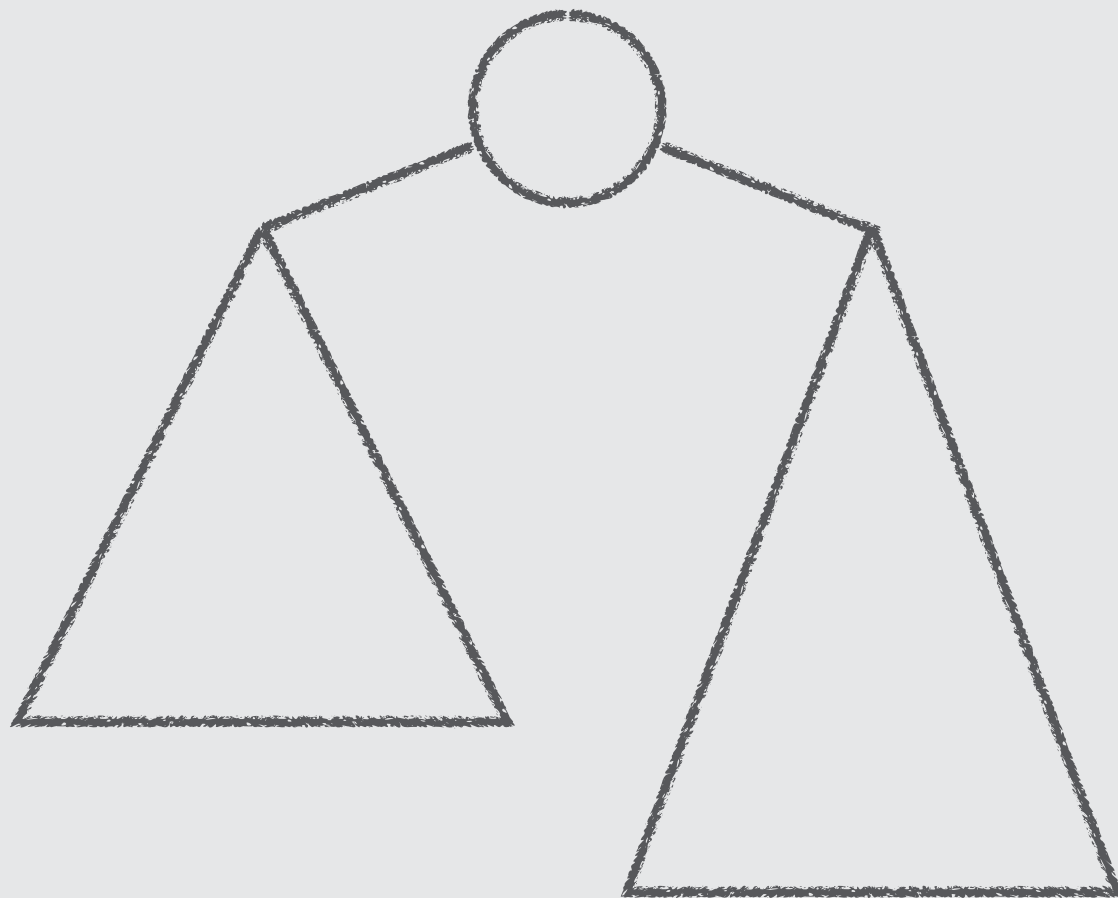
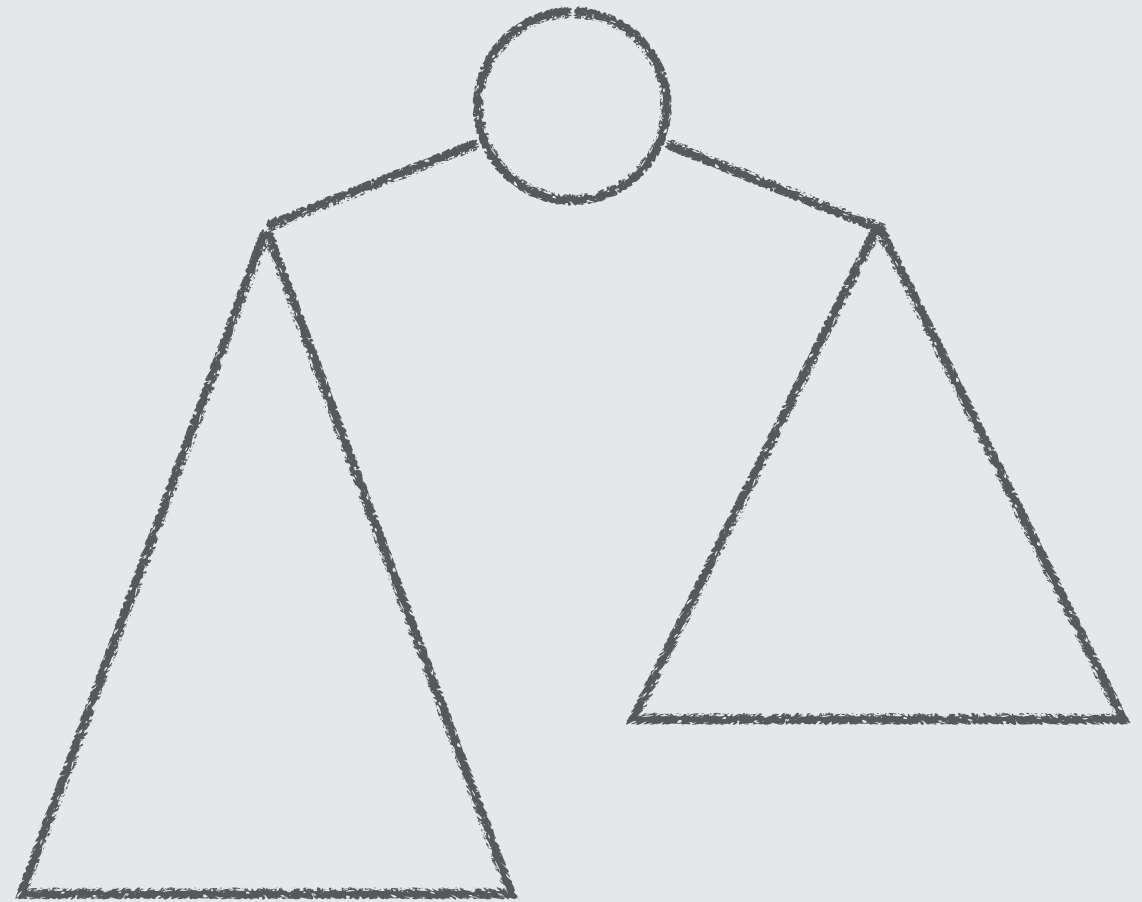
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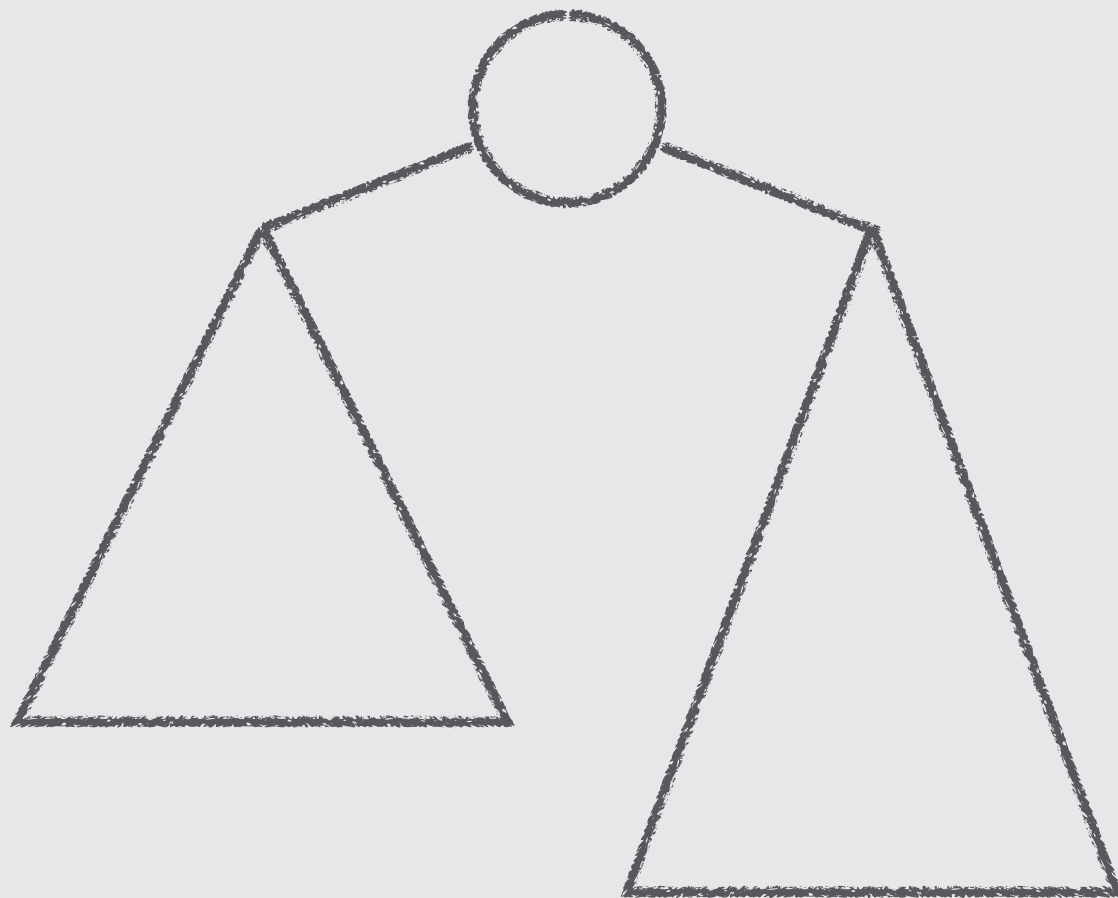
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QUESTIONS?

THANK YOU!